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LISY300AL

MEMS inertial sensor:

single-axis ±300°/s analog output yaw rate gyroscope

Features

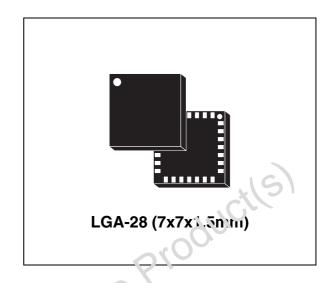
- 2.7 V to 3.6 V single supply operation
- Low power consumption
- Embedded power-down
- ±300 °/s full scale
- Absolute analog rate output
- Integrated low-pass filters
- Embedded self-test
- High shock survivability
- ECOPACK[®] RoHS and "Green" compliant (see *Section 4*)



The LISY300AL is a low-power single-axis yaw rate sensor. It includes a sensing element and an IC interface able to provide the measured angular rate to the external world through an analog output voltage.

The sensing element, capable of detecting the yaw rate, is manufactured using a dedica od micromachining process developed by ST to produce inertial sensors and actualors on silicon wafers.

The IC interface is manufactured using a CMOS process that allows a nigh level of integration to design a dedicated circuit which is trimmed to better match the sensing element characteristics.



The LISY30 A! nas a full scale of ±300 °/s and is capable of measuring rates with a -3 dB bar awath up to 88 Hz.

The LISY300AL is available in a plastic land grid array (LGA) package and can operate within a temperature range from -40 °C to +85 °C.

The LISY300AL belongs to a family of products suitable for a variety of applications, including:

- Gaming and virtual reality input devices
- Motion control with MMI (man-machine interface)
- Image stabilization for digital video and digital still cameras
- GPS navigation systems
- Appliances and robotics

Table 1. Device summary

| Order code | Temperature range (°C) | Package | Packing |
|-------------|------------------------|------------------|---------------|
| LISY300AL | -40 to +85 | LGA-28 (7x7x1.5) | Tray |
| LISY300ALTR | -40 to +85 | LGA-28 (7x7x1.5) | Tape and reel |

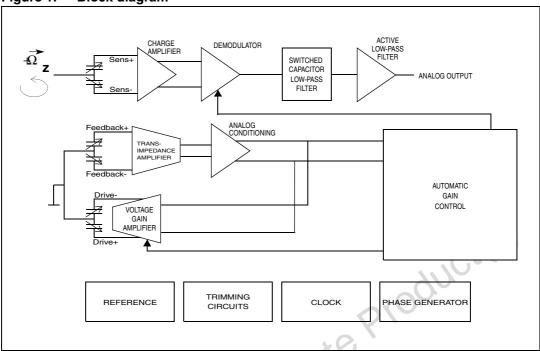
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1 Block diagram and pin description

Figure 1. Block diagram



The vibration of the structure is maintained by a drive circuitry in a feedback loop. The sensing signal is filtered and appears as an analog signal at the output.

1.1 Pin description

Figure 2. Pin connection

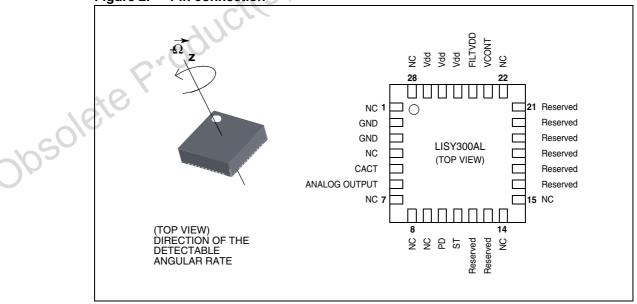


Table 2. Pin description

| Pin # | | Function | |
|--------------------|------------------|---|--|
| | Pin Name NC | Internally not connected | |
| 2 | GND | 0V supply | |
| 3 | GND | 0V supply | |
| 4 | NC | Internally not connected | |
| 5 | CACT | Active filter capacitor | |
| 6 | ANALOG OUTPUT | Rate signal output voltage | |
| 7-9 | NC | Internally not connected | |
| 10 | PD | Power-down (logic 0: normal mode; logic 1: power-down mode) | |
| 11 | ST | Self-test (logic 0: normal mode; logic 1: self-test) | |
| 12-13 | Reserved | Leave unconnected | |
| 14-15 | NC | Internally not connected | |
| 16-21 | Reserved | Leave unconnected | |
| 22 | NC | Internally not connected | |
| 23 | VCONT | PLL filter connection pad #1 | |
| 24 | FILTVDD | PLL filter connection pad #2 | |
| 25 | Vdd | Power supply | |
| 26 | Vdd | Power supply | |
| 27 | Vdd | Power supply | |
| 28 | NC | Internally not connected | |
| psolete Product(s) | | | |

2 Mechanical and electrical specifications

2.1 Mechanical characteristics

Table 3. Mechanical characteristics @ Vdd = 3.3 V, T = 25 °C unless otherwise noted⁽¹⁾

| Symbol | Parameter | Test condition | Min. | Typ. ⁽²⁾ | Max. | Unit |
|--------|--|--------------------------|-------------|---------------------|----------|--------------|
| FS | Measurement range | | | ±300 | | °/s |
| So | Sensitivity | | | 3.3 | | mV/ °/s |
| SoDr | Sensitivity change vs. temperature | From -40 °C to +85 °C | | 4 | | % |
| Voff | Zero-rate level ⁽³⁾ | | | 1.65 | | V |
| OffDr | Zero-rate level change vs. temperature | From -40 °C to +85 °C | | 5 | | °/s |
| NL | Non linearity ⁽⁴⁾ | Best fit straight line | | ±0.8 | | % FS |
| BW | -3dB bandwidth(3)(5) | C _{ACT} = 10 nF | | 88 | | Hz |
| Rn | Rate noise density | | | 0.1 | 11 1C/11 | °/s / √Hz |
| Vt | Self-test output voltage change ⁽⁶⁾ | | | +300 | 00.0 | mV |
| Sup | Start-up time | Settling to ±5 °/s | | 300 | | ms |
| Fres | Sensing element resonant frequency | | 16, | 4.5 | | kHz |
| Тор | Operating temperature range | | G-40 | | +85 | °C |
| Wh | Product weight | | | 160 | | mg |

^{1.} The product is factory calibrated at 3.3 V. The operational power supply range is specified in *Table 4*.

^{2.} Typical specifications are not guaranteed

^{3.} The product is capable of sensing angular rates extending from DC to the selected bandwidth

^{4.} Guaranteed by design

^{5.} User selectable by external capacitor CACT

^{6. &}quot;Self-test output voltage change" is defined as Vout_(Vst = logic 1) - Vout_(Vst = logic 0)

2.2 **Electrical characteristics**

Electrical characteristics @ Vdd =3.3 V, T=25 °C unless otherwise noted⁽¹⁾ Table 4.

| Symbol | Parameter | Test condition | Min. | Typ. ⁽²⁾ | Max. | Un |
|-------------------|--|-------------------------|---------|---------------------|----------------------|----|
| Vdd | Supply voltage | | 2.7 | 3.3 | 3.6 | ٧ |
| ldd | Supply current | PD pin connected to GND | | 4.8 | | m. |
| IddPdn | Supply current in power-down mode | PD pin connected to Vdd | | 1 | | μΑ |
| VsT | Self-test input | Logic 0 level | 0 | | 0.2*Vdd | V |
| VSI | Sen-test input | Logic 1 level | 0.8*Vdd | | Vdd | |
| VPD | Power-down input | Logic 0 level | 0 | | 0.2*Vdd | V |
| VID | 1 ower-down input | Logic 1 level | 0.8*Vdd | | Vdd | V |
| C _{ACT} | Active low-pass filter capacitor | | 10 | | | nl |
| ovs | Output voltage swing ⁽³⁾ | lout = ±100μA | 0.4 | | V _{dd} -0.4 | V |
| C _{LOAD} | Capacitive load drive ⁽³⁾ | | 0.4 | | 10 | nl |
| Тор | Operating temperature range | | -40 | | +85 | °(|
| 2. Typical spe | ct is factory calibrated at 3.3 V ecifications are not guaranteed o ANALOG OUTPUT pin #6 | i | olețe | Plo | | |
| 2. Typical spe | ct is factory calibrated at 3.3 V ecifications are not guaranteed o ANALOG OUTPUT pin #6 | | olete | PIC | | |

Absolute maximum ratings 2.3

Stresses above those listed as "Absolute maximum ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device under these conditions is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

Table 5. **Absolute maximum ratings**

| Symbol | Ratings | Maximum value | Unit |
|------------------|---|--------------------|------|
| Vdd | Supply voltage | -0.3 to 6 | V |
| Vin | Input voltage on any control pin (PD, ST) | -0.3 to Vdd +0.3 | V |
| ۸ | Acceleration (not powered) | 3000 g for 0.5 ms | |
| A _{UNP} | Acceleration (not powered) | 10000 g for 0.1 ms | |
| T _{STG} | Storage temperature range | -40 to +125 | °C |
| ESD | Electrostatic discharge protection | 2 (HBM) | kV |



This is a mechanical shock sensitive device, improper handling can cause permanent damage to the part



obsolete Product(s). Obsolete Product(s). This is an ESD sensitive device, improper handling can cause permanent damage to

2.4 Terminology

2.4.1 Sensitivity

A yaw rate gyroscope is a Z-axis rate device that produces a positive-going output voltage for counterclockwise rotation around the axis normal to the package top. Sensitivity describes the gain of the sensor and can be determined by applying a defined angular velocity to it. This value changes very little over temperature and also very little over time.

2.4.2 Zero-rate level

Zero-rate level describes the actual output signal if there is no angular rate present. For a 3.3 V powered sensor the absolute zero-rate output is ideally 1.65 V. Zero-rate level of precise MEMS sensors is, to some extent, a result of stress to the sensor and therefore zero-rate level can slightly change after mounting the sensor onto a printed circuit board or after exposing it to extensive mechanical stress. This value changes very little over temperature and also very little over time.

2.4.3 Self-test

Obsolete Product(s)

Self-test allows to test the mechanical and electric part of the sensor, allowing the seismic mass to be moved by means of an electrostatic test-force. The Self-test function is off when the ST pin is connected to GND. When the ST pin is tied to Vdd, an actuation force is applied to the sensor, emulating a definite Coriolis force. In this case the sensor output will exhibit a voltage change in its DC level which is also depending on the supply voltage. When ST is active, the device output level is given by the algebraic sum of the signals produced by the velocity acting on the sensor and by the electrostatic test-force. If the output signals change within the amplitude specified in *Table 3*, then the mechanical element is working properly and the parameters of the interface chip are within the defined specification.

LISY300AL Application hints

3 Application hints

C2 450nF GND **GND VDD** 9.5kOhm 100 nF R1 C1] 1 \bigcirc 20 Optional 19 Low-pass filter LISY300AL 18 (top view) 17 16 15 C_{LOAD} Digital signals

Figure 3. LISY300AL electrical connections and external components values

Power supply decoupling capacitors (100 nF ceramic or polyester + 10 μ F Aluminum) should be placed as near as possible to the device (common design practice).

The LISY300AL allows to band limit the output rate response through the use of two first-order on-chip filters: a switched capacitor low-pass filter, with 400Hz -3dB bandwidth, in combination with an active low-pass filter. The active filter -3 dB nominal frequency (f_{tA}) is set through an internal resistor R_{ACT} and the external capacitor C_{ACT} (added between **CACT** pin #5 and **ANALOG OUTPUT** pin #6), by the formula:

$$f_{tA} = \frac{1}{2\pi \cdot R_{ACT} \cdot C_{ACT}}$$

The value of the internal resistor R_{ACT} is 180 k Ω , while the external capacitor C_{ACT} is used to select the signal bandwidth. The sensed frequency range spans from DC up to the selected bandwidth.

In order to further reduce high-frequency noise, the LISY300AL supports an additional optional low-pass filter on **ANALOG OUTPUT** pin #6 (*Figure 3*). The cutoff frequency (f_{tP}) is given by the formula:

$$f_{tP} = \frac{1}{2\pi \cdot R_{OPT} \cdot C_{OPT}}$$

Application hints LISY300AL

> The LISY300AL IC includes a PLL (phase locked loop) circuit to synchronize driving and sensing interfaces. Capacitors and resistors must be added at the FILTVDD and VCONT pads (as shown in Figure 3) to implement a second-order low-pass filter. Table 6 summarizes the PLL low-pass filter components' values.

Table 6. PLL low-pass filter components' values

| Component | Value |
|-----------|--------------|
| C1 | 450 nF ± 10% |
| C2 | 9 nF ± 10% |
| R1 | 9.5 kΩ± 10% |

3.1 **Soldering information**

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The LGA package is compliant with the ECOPACK®, RoHS and "Green" standard. It is qualified for soldering heat resistance according to JEDEC J-STD-020C.

Leave "Pin 1 Indicator" unconnected during soldering.

obsolete Product(s). Land pattern and soldering recommendations are available at www.st.com/mems

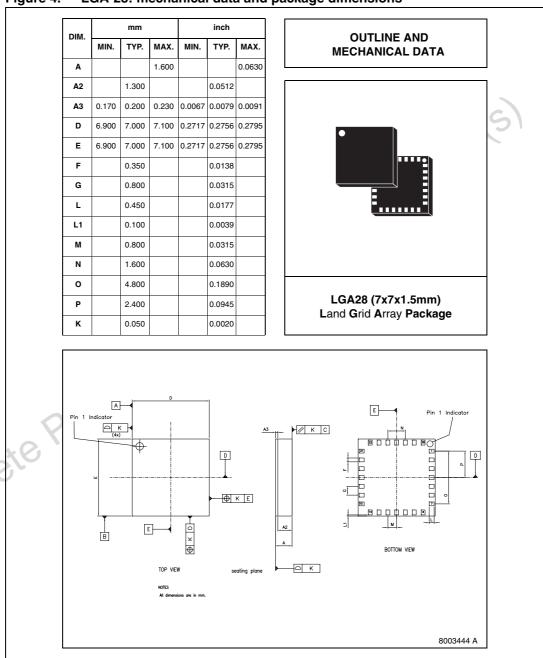
LISY300AL Package information

4 Package information

In order to meet environmental requirements, ST offers these devices in ECOPACK® packages. These packages have a lead-free second level interconnect. The category of second level interconnect is marked on the inner box label, in compliance with JEDEC Standard JESD97. The maximum ratings related to soldering conditions are also marked on the inner box label. ECOPACK® is an ST trademark.

ECOPACK® specifications are available at: www.st.com.

Figure 4. LGA-28: mechanical data and package dimensions



Revision history LISY300AL

5 Revision history

Table 7. Document revision history

| Date | Revision | Changes |
|-----------|----------|-----------------|
| 29-May-08 | 1 | Initial release |



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