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4 O/P 1.8V PCIe Gen1-2-3 ZDB/FOB w/Zo=100ohm

DATASHEET

Description

The 9DBV0441 is a member of IDT's SOC-Friendly 1.8V Very-Low-Power (VLP) PCIe family. It has integrated output terminations providing Zo=100ohms for direct connection to 100ohm transmission lines. The device has 4 output enables for clock management, and 3 selectable SMBus addresses.

Recommended Application

1.8V PCIe Gen1-2-3 Zero-Delay/Fan-out Buffer (ZDB/FOB)

Output Features

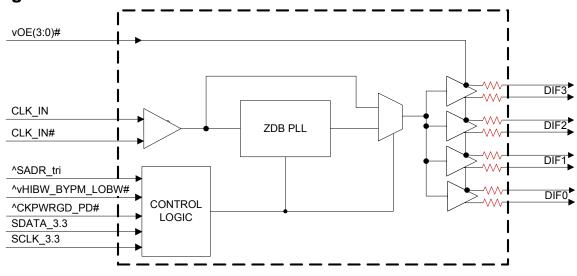
• 4 – 1-200Hz Low-Power (LP) HCSL DIF pairs w/Zo=100 Ω

Key Specifications

- DIF cycle-to-cycle jitter <50ps
- DIF output-to-output skew <50ps
- DIF additive phase jitter is <100fs rms for PCIe Gen3
- DIF additive phase jitter <300fs rms for 12kHz-20MHz

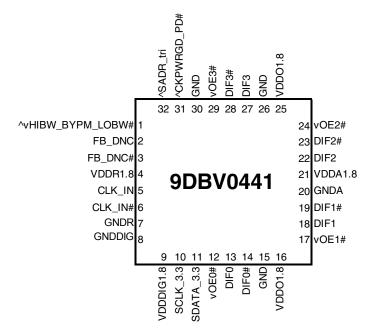
Features/Benefits

- Direct connection to 100ohm transmission lines; saves 16 resistors compared to standard HCSL outputs
- 53mW typical power consumption in PLL mode; minimal power consumption
- Spread Spectrum (SS) compatible; allows use of SS for EMI reduction
- OE# pins; support DIF power management
- HCSL compatible differential input; can be driven by common clock sources
- Programmable Slew rate for each output; allows tuning for various line lengths
- Programmable output amplitude; allows tuning for various application environments
- Pin/software selectable PLL bandwidth and PLL Bypass; minimize phase jitter for each application
- Outputs blocked until PLL is locked; clean system start-up
- Software selectable 50MHz or 125MHz PLL operation; useful for Ethernet applications
- Configuration can be accomplished with strapping pins; SMBus interface not required for device control
- 3.3V tolerant SMBus interface works with legacy controllers
- Space saving 32-pin 5x5mm VFQFPN; minimal board space
- Selectable SMBus addresses; multiple devices can easily share an SMBus segment



Block Diagram

Pin Configuration



32-pin VFQFPN, 5x5 mm, 0.5mm pitch

^ prefix indicates internal 120KOhm pull up resistor
 ^v prefix indicates internal 120KOhm pull up AND pull down resistor (biased to VDD/2)
 v prefix indicates internal 120KOhm pull down resistor

SMBus Address Selection Table

	SADR	Address	+ Read/Write bit
State of SADR on first application of	0	1101011	Х
CKPWRGD PD#	М	1101100	Х
	1	1101101	х

Power Management Table

CKPWRGD PD#	CLK IN	SMBus	OEx# Pin	DIF	x	PLL	
	CER_IN	OEx bit	True O/P		Comp. O/P		
0	Х	Х	Х	Low	Low	Off	
1	Running	0	Х	Low	Low	On ¹	
1	Running	1	0	Running	Running	On ¹	
1	Running	1	1	Low	Low	On ¹	

1. If Bypass mode is selected, the PLL will be off, and outputs will be running.

Power Connections

Pin Numb	Pin Number				
VDD	GND	Description			
4	7	Input receiver analog			
9	8	Digital Power			
16, 25	15,20,26,30	DIF outputs			
21	20	PLL Analog			

Frequency Select Table

FSEL	CLK_IN	DIFx
Byte3 [4:3]	(MHz)	(MHz)
00 (Default)	100.00	CLK_IN
01	50.00	CLK_IN
10	125.00	CLK_IN
11	Reserved	Reserved

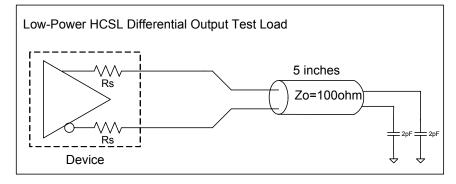
PLL Operating Mode

		Byte1 [7:6]	Byte1 [4:3]
HiBW_BypM_LoBW#	MODE	Readback	Control
0	PLL Lo BW	00	00
М	Bypass	01	01
1	PLL Hi BW	11	11

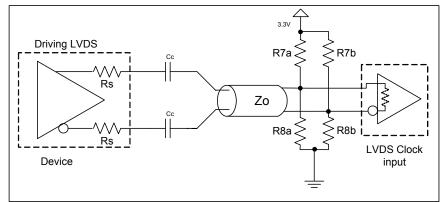
Pin Descriptions

Pin#	Pin Name	Туре	Pin Description
1	^vHIBW BYPM LOBW#	LATCHED IN	Trilevel input to select High BW, Bypass or Low BW mode.
1	VHIBW_BYPM_LOBW#		See PLL Operating Mode Table for Details.
2	FB_DNC	DNC	True clock of differential feedback. The feedback output and feedback input are
2	FB_DINC	DNC	connected internally on this pin. Do not connect anything to this pin.
3	FB DNC#	DNC	Complement clock of differential feedback. The feedback output and feedback
3	FB_DNC#	DNC	input are connected internally on this pin. Do not connect anything to this pin.
4	VDDR1.8	PWR	1.8V power for differential input clock (receiver). This VDD should be treated as
4			an Analog power rail and filtered appropriately.
5	CLK_IN	IN	True Input for differential reference clock.
6	CLK_IN#	IN	Complementary Input for differential reference clock.
7	GNDR	GND	Analog Ground pin for the differential input (receiver)
8	GNDDIG	GND	Ground pin for digital circuitry
9	VDDDIG1.8	PWR	1.8V digital power (dirty power)
10	SCLK_3.3	IN	Clock pin of SMBus circuitry, 3.3V tolerant.
11	SDATA_3.3	I/O	Data pin for SMBus circuitry, 3.3V tolerant.
12	vOE0#	IN	Active low input for enabling DIF pair 0. This pin has an internal pull-down.
			1 =disable outputs, 0 = enable outputs
13	DIF0	OUT	Differential true clock output
14	DIF0#	OUT	Differential Complementary clock output
15	GND	GND	Ground pin.
16	VDDO1.8	PWR	Power supply for outputs, nominally 1.8V.
17	vOE1#	IN	Active low input for enabling DIF pair 1. This pin has an internal pull-down.
	-		1 =disable outputs, 0 = enable outputs
18	DIF1	OUT	Differential true clock output
19	DIF1#	OUT	Differential Complementary clock output
20	GNDA	GND	Ground pin for the PLL core.
21	VDDA1.8	PWR	1.8V power for the PLL core.
22	DIF2	OUT	Differential true clock output
23	DIF2#	OUT	Differential Complementary clock output
24	vOE2#	IN	Active low input for enabling DIF pair 2. This pin has an internal pull-down.
			1 =disable outputs, 0 = enable outputs
25	VDDO1.8	PWR	Power supply for outputs, nominally 1.8V.
26	GND	GND	Ground pin.
27	DIF3	OUT	Differential true clock output
28	DIF3#	OUT	Differential Complementary clock output
29	vOE3#	IN	Active low input for enabling DIF pair 3. This pin has an internal pull-down.
-			1 =disable outputs, 0 = enable outputs
30	GND	GND	Ground pin.
			Input notifies device to sample latched inputs and start up on first high assertion.
31	^CKPWRGD_PD#	IN	Low enters Power Down Mode, subsequent high assertions exit Power Down
			Mode. This pin has internal pull-up resistor.
32	^SADR_tri	LATCHED IN	Tri-level latch to select SMBus Address. See SMBus Address Selection Table.

Test Loads



Driving LVDS



Driving LVDS inputs

	N N		
	Receiver has	Receiver does not	
Component	termination have termination		Note
R7a, R7b	10K ohm	140 ohm	
R8a, R8b	5.6K ohm	75 ohm	
Cc	0.1 uF	0.1 uF	
Vcm	1.2 volts	1.2 volts	

Absolute Maximum Ratings

Stresses above the ratings listed below can cause permanent damage to the 9DBV0441. These ratings, which are standard values for IDT commercially rated parts, are stress ratings only. Functional operation of the device at these or any other conditions above those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods can affect product reliability. Electrical parameters are guaranteed only over the recommended operating temperature range.

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	МАХ	UNITS	NOTES
Supply Voltage	VDDx	Applies to all VDD pins	-0.5		2.5	V	1,2
Input Voltage	V _{IN}		-0.5		V_{DD} +0.5V	V	1, 3
Input High Voltage, SMBus	VIHSMB	SMBus clock and data pins			3.6V	V	1
Storage Temperature	Ts		-65		150	°C	1
Junction Temperature	Tj				125	°C	1
Input ESD protection	ESD prot	Human Body Model	2000			V	1

¹Guaranteed by design and characterization, not 100% tested in production.

² Operation under these conditions is neither implied nor guaranteed.

³ Not to exceed 2.5V.

Electrical Characteristics–Clock Input Parameters

TA = T_{COM} or T_{IND;} Supply Voltage per VDD of normal operation conditions, See Test Loads for Loading Conditions

			0				
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Input High Voltage - DIF_IN	V _{IHDIF}	Differential inputs (single-ended measurement)	600	800	1150	mV	1
Input Low Voltage - DIF_IN	V _{ILDIF}	Differential inputs (single-ended measurement)	V _{SS} - 300	0	300	mV	1,3
Input Common Mode Voltage - DIF_IN	V _{COM}	Common Mode Input Voltage	300		725	mV	1
Input Amplitude - DIF_IN	V _{SWING}	Peak to Peak value (V _{IHDIF} - V _{ILDIF})	300		1450	mV	1
Input Slew Rate - DIF_IN	dv/dt	Measured differentially	0.4			V/ns	1,2
Input Leakage Current	I _{IN}	$V_{IN} = V_{DD}$, $V_{IN} = GND$	-5		5	uA	1
Input Duty Cycle	d _{tin}	Measurement from differential wavefrom	45		55	%	1
Input Jitter - Cycle to Cycle	J _{DIFIn}	Differential Measurement	0		150	ps	1

¹ Guaranteed by design and characterization, not 100% tested in production.

² Slew rate measured through +/-75mV window centered around differential zero

³ The device can be driven from a single ended clock by driving the true clock and biasing the complement clock input to the V_{BIAS} , where V_{BIAS} is ($V_{IHHIGH} - V_{IHLOW}$)/2

Electrical Characteristics–Input/Supply/Common Parameters–Normal Operating Conditions

TA = TCOM OF TIND SUPP	v Voltage per VDD of normal	l operation conditions. Se	ee Test Loads for Loading Co	onditions
	y voltage per vee or norma	i oporation oonationo, o	too root coudo for couding oc	nantionio

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
1.8V Supply Voltage	VDD	Supply voltage for core, analog and LVCMOS outputs	1.7	1.8	1.9	V	1
Ambient Operating	T _{COM}	Commmercial range	0	25	70	ů	1
Temperature	T _{IND}	Industrial range	-40	25	85	°C	1
Input High Voltage	V _{IH}	Single-ended inputs, except SMBus	$0.75 V_{DD}$		$V_{DD} + 0.3$	V	1
Input Mid Voltage	VIM	Single-ended tri-level inputs ('_tri' suffix)	$0.4 V_{DD}$		0.6 V _{DD}	V	1
Input Low Voltage	V _{IL}	Single-ended inputs, except SMBus	-0.3		$0.25 V_{DD}$	V	1
	I _{IN}	Single-ended inputs, $V_{IN} = GND$, $V_{IN} = VDD$	-5		5	uA	1
Input Current	I _{INP}	Single-ended inputs $V_{IN} = 0 V$; Inputs with internal pull-up resistors $V_{IN} = VDD$; Inputs with internal pull-down resistors	-200		200	uA	1
	F _{ibyp}	Bypass mode	1		200	MHz	2
	F _{ipll100}	100MHz PLL mode	50	100.00	140	MHz	2
Input Frequency	F _{ipll125}	125MHz PLL mode	62.5	125.00	175	V °C V UA MHz MHz MHz PF PF PF MS KHz clocks us Ns V V V V V V V V	2
	F _{ipll62}	50MHz PLL mode	25	50.00	65	MHz	2
Pin Inductance	L _{pin}				7	nH	1
	C _{IN}	Logic Inputs, except DIF_IN	1.5		5	pF	1
Capacitance	CINDIF IN	DIF_IN differential clock inputs	1.5		2.7	pF	1,6
	COUT	Output pin capacitance			6	V °C V V V UA UA MHz MHz MHz MHz MHz MHz MHz MHz	1
Clk Stabilization	T _{STAB}	From V _{DD} Power-Up and after input clock stabilization or de-assertion of PD# to 1st clock		0.6	1	ms	1,2
Input SS Modulation Frequency	f _{MODIN}	Allowable Frequency (Triangular Modulation)	30	31.500	33	kHz	1
OE# Latency	t _{LATOE#}	DIF start after OE# assertion DIF stop after OE# deassertion	1		3	clocks	1,3
Tdrive_PD#	t _{DRVPD}	DIF output enable after PD# de-assertion			300	us	1,3
Tfall	t _F	Fall time of single-ended control inputs			5	ns	1,2
Trise	t _R	Rise time of single-ended control inputs			5	ns	1,2
SMBus Input Low Voltage	VILSMB	V_{DDSMB} = 3.3V, see note 4 for V_{DDSMB} < 3.3V			0.8	V	1, 4
SMBus Input High Voltage	VIHSMB	V_{DDSMB} = 3.3V, see note 5 for V_{DDSMB} < 3.3V	2.1		3.6	-	1, 5
SMBus Output Low Voltage	VOLSMB	@ I _{PULLUP}			0.4	V	1
SMBus Sink Current	I _{PULLUP}	@ V _{OL}	4			mA	1
Nominal Bus Voltage	V _{DDSMB}		1.7		3.6	V	1
SCLK/SDATA Rise Time	t _{RSMB}	(Max VIL - 0.15) to (Min VIH + 0.15)			1000	ns	1
SCLK/SDATA Fall Time	t _{FSMB}	(Min VIH + 0.15) to (Max VIL - 0.15)			300	ns	1
SMBus Operating Frequency	f _{MAXSMB}	Maximum SMBus operating frequency			400	kHz	1,7

¹Guaranteed by design and characterization, not 100% tested in production.

²Control input must be monotonic from 20% to 80% of input swing.

³Time from deassertion until outputs are >200 mV

 4 For V_{DDSMB} < 3.3V, V_{ILSMB} <= 0.35V_{DDSMB}

 5 For V_{DDSMB} < 3.3V, V_{IHSMB} >= 0.65V_{DDSMB}

⁶DIF_IN input

⁷The differential input clock must be running for the SMBus to be active

Electrical Characteristics–DIF 0.7V Low Power HCSL Outputs

TA = T_{COM} or T_{IND}; Supply Voltage per VDD of normal operation conditions, See Test Loads for Loading Conditions

		,	0				
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Slew rate	Trf	Scope averaging on 3.0V/ns setting	1.1	2	3	V/ns	1, 2, 3
Siew fale		Scope averaging on 2.0V/ns setting	1.9	3	4	V/ns	1, 2, 3
Slew rate matching	∆Trf	Slew rate matching, Scope averaging on		7	20	%	1, 2, 4
Voltage High	V _{HIGH}	Statistical measurement on single-ended signal using oscilloscope math function. (Scope	660	774	850	mV	1,7
Voltage Low	V _{LOW}	averaging on)	-150	18	150		1,7
Max Voltage	Vmax	Measurement on single ended signal using		821	1150	mV	1
Min Voltage	Vmin	absolute value. (Scope averaging off)	-300	-15			1
Vswing	Vswing	Scope averaging off	300	1536		mV	1,2,7
Crossing Voltage (abs)	Vcross_abs	Scope averaging off	250	414	550	mV	1,5,7
Crossing Voltage (var)	∆-Vcross	Scope averaging off		13	140	mV	1, 6

¹Guaranteed by design and characterization, not 100% tested in production.

² Measured from differential waveform

³ Slew rate is measured through the Vswing voltage range centered around differential 0V. This results in a +/-150mV window around differential 0V.

⁴ Matching applies to rising edge rate for Clock and falling edge rate for Clock#. It is measured using a +/-75mV window centered on the average cross point where Clock rising meets Clock# falling. The median cross point is used to calculate the voltage thresholds the oscilloscope is to use for the edge rate calculations.

⁵ Vcross is defined as voltage where Clock = Clock# measured on a component test board and only applies to the differential rising edge (i.e. Clock rising and Clock# falling).

⁶ The total variation of all Vcross measurements in any particular system. Note that this is a subset of Vcross_min/max (Vcross absolute) allowed. The intent is to limit Vcross induced modulation by setting Δ-Vcross to be smaller than Vcross absolute.

⁷ At default SMBus settings.

Electrical Characteristics–Current Consumption

TA = T_{COM} or T_{IND}: Supply Voltage per VDD of normal operation conditions, See Test Loads for Loading Conditions

				0			
PARAMETER	SYMBOL	CONDITIONS	MIN	MIN TYP MAX UNITS N 11 15 mA 1 25 35 mA 1 11 12 mA 1 12 1 mA 1 1.2 mA 1 1	NOTES		
Operating Supply Current	I _{DDAOP}	VDDA+VDDR, PLL Mode, @100MHz		11	15	mA	1
Operating Supply Current	I _{DDOP}	VDD1.8, All outputs active @100MHz		25	35	mA	1
Powerdown Current	I _{DDAPD}	VDDA+VDDR, PLL Mode, @100MHz			1	mA mA mA	1,2
r owerdown Current	I _{DDPD}	VDD1.8, Outputs Low/Low			1.2	mA	1, 2

¹ Guaranteed by design and characterization, not 100% tested in production.

² Input clock stopped.

Electrical Characteristics–Output Duty Cycle, Jitter, Skew and PLL Characteristics

TA = T_{COM} or T_{IND}. Supply Voltage per VDD of normal operation conditions, See Test Loads for Loading Conditions

TA = 1 COM OF TIND, Supply Voltage per VDD of normal operation conditions, See Test Loads for Loading Conditions					15		
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
PLL Bandwidth	BW	-3dB point in High BW Mode	2	2.7	4	MHz	1,5
FLL Bandwidth	DVV	-3dB point in Low BW Mode	1	1.4	2	MHz	1,5
PLL Jitter Peaking	t _{JPEAK}	Peak Pass band Gain		1.2	2	dB	1
Duty Cycle	t _{DC}	Measured differentially, PLL Mode	45	50.1	55	%	1
Duty Cycle Distortion	t _{DCD}	Measured differentially, Bypass Mode @100MHz	-1	0	1	%	1,3
Skow Input to Output	t _{pdBYP}	Bypass Mode, V _T = 50%	3000	3600	4500	ps	1
Skew, Input to Output	t _{pdPLL}	PLL Mode V _T = 50%	0	92	200	ps	1,4
Skew, Output to Output	t _{sk3}	V _T = 50%		28	50	ps	1,4
Jitter, Cycle to cycle	+	PLL mode		16	50	ps	1,2
	t _{jcyc-cyc}	Additive Jitter in Bypass Mode		0.1	25	ps	1,2

¹ Guaranteed by design and characterization, not 100% tested in production.

² Measured from differential waveform

³ Duty cycle distortion is the difference in duty cycle between the output and the input clock when the device is operated in bypass mode.

⁴ All outputs at default slew rate

⁵ The MIN/TYP/MAX values of each BW setting track each other, i.e., Low BW MAX will never occur with Hi BW MIN.

Electrical Characteristics–Phase Jitter Parameters

TA = T_{COM} or T_{IND;} Supply Voltage per VDD of normal operation conditions, See Test Loads for Loading Conditions

						INDUSTRY		
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	LIMIT	UNITS	Notes
	t _{iphPCleG1}	PCIe Gen 1		34	52	86	ps (p-p)	1,2,3
	+	PCIe Gen 2 Lo Band 10kHz < f < 1.5MHz		0.9	1.4	3	ps (rms)	1,2
Phase Jitter, PLL Mode	t _{jphPCleG2}	PCIe Gen 2 High Band 1.5MHz < f < Nyquist (50MHz)		2.2	2.5	3.1	ps (rms)	1,2
	t _{jphPCleG3}	PCIe Gen 3 (PLL BW of 2-4MHz, CDR = 10MHz)		0.5	0.6	1	ps (rms)	1,2,4
	t _{jphSGMII}	125MHz, 1.5MHz to 20MHz, -20dB/decade rollover < 1.5MHz, -40db/decade rolloff > 10MHz		1.9	2	NA	ps (rms)	1,6
	t _{jphPCleG1}	PCle Gen 1		0.6	5	N/A	ps (p-p)	1,2,3
	+	PCIe Gen 2 Lo Band 10kHz < f < 1.5MHz		0.1	0.3	N/A	ps (rms)	1,2,5
	t _{jphPCleG2}	PCIe Gen 2 High Band 1.5MHz < f < Nyquist (50MHz)		0.05	0.1	N/A	ps (rms)	1,2,5
Additive Phase Jitter, Bypass Mode	t _{jphPCleG3}	PCIe Gen 3 (PLL BW of 2-4MHz, CDR = 10MHz)		0.05	0.1	N/A	ps (rms)	1,2,4, 5
	t _{jphSGMIIM0}	125MHz, 1.5MHz to 10MHz, -20dB/decade rollover < 1.5MHz, -40db/decade rolloff > 10MHz		165	200	N/A	fs (rms)	1,6
	t _{jphSGMIIM1}	125MHz, 12kHz to 20MHz, -20dB/decade rollover < 1.5MHz, -40db/decade rolloff > 10MHz		251	300	N/A	fs (rms)	1,6

¹Guaranteed by design and characterization, not 100% tested in production.

² See http://www.pcisig.com for complete specs

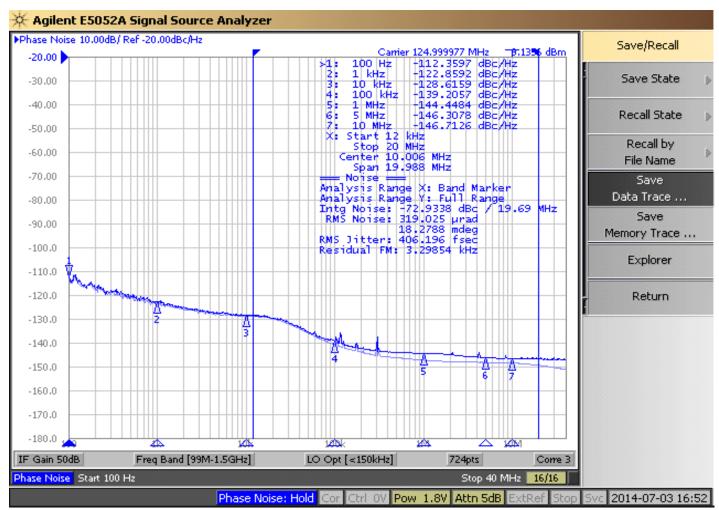
⁴ For RMS figures, additive jitter is calculated by solving the following equation: Additive jitter = SQRT[(total jitter)^2 - (input jitter)^2]

⁵ Driven by 9FGV0831 or equivalent

⁶ Driven by Rohde&Schwarz SMA100

³ Sample size of at least 100K cycles. This figures extrapolates to 108ps pk-pk @ 1M cycles for a BER of 1-12.

Additive Phase Jitter Plot: 125M (12kHz to 20MHz)



How to Write

DIDT

- Controller (host) sends a start bit
- Controller (host) sends the write address
- IDT clock will acknowledge
- Controller (host) sends the beginning byte location = N
- IDT clock will acknowledge
- Controller (host) sends the byte count = X
- IDT clock will acknowledge
- Controller (host) starts sending Byte N through Byte N+X-1
- IDT clock will acknowledge each byte one at a time
- Controller (host) sends a Stop bit

	Index Blo	ock V	Vrite Operation
Controll	er (Host)		IDT (Slave/Receiver)
Т	starT bit		
Slave A	Adress		
WR	WRite		
			ACK
Beginning	g Byte = N		
			ACK
Data Byte	Count = X		
			ACK
Beginnin	g Byte N	×	
		X Byte	ACK
0			
0			0
0			0
			0
Byte N	+ X - 1		
			ACK
Р	stoP bit		

Note: SMBus Address is Latched on SADR pin.

How to Read

- Controller (host) will send a start bit
- Controller (host) sends the write address
- IDT clock will acknowledge
- Controller (host) sends the beginning byte location = N
- IDT clock will acknowledge
- Controller (host) will send a separate start bit
- Controller (host) sends the read address
- IDT clock will acknowledge
- IDT clock will send the data byte count = X
- IDT clock sends Byte N+X-1
- IDT clock sends Byte 0 through Byte X (if X_(H) was written to Byte 8)
- Controller (host) will need to acknowledge each byte
- Controller (host) will send a not acknowledge bit
- Controller (host) will send a stop bit

	Index Block R	ead C	peration
Co	ntroller (Host)		IDT (Slave/Receiver)
Т	starT bit	-	
SI	ave Address	-	
WR	WRite	-	
		-	ACK
Begi	nning Byte = N	-	
		-	ACK
RT	Repeat starT	-	
SI	ave Address		
RD	ReaD		
			ACK
		-	Data Byte Count=X
	ACK		
			Beginning Byte N
	ACK	-	
		-	0
	0	-	0
	0	a	0
	0	X Byte	
	r	×	Byte N + X - 1
N	Not acknowledge		
Р	stoP bit		

Byte 0	Name	Control Function	Туре	0	1	Default
Bit 7		Reserved				1
Bit 6	DIF OE3	Output Enable	RW	Low/Low	Enabled	1
Bit 5	DIF OE2	Output Enable	RW	Low/Low	Enabled	1
Bit 4		Reserved				
Bit 3	DIF OE1	Output Enable	RW	Low/Low	Enabled	1
Bit 2		Reserved				1
Bit 1	DIF OE0	Output Enable	RW	Low/Low	Enabled	1
Bit 0		Reserved				

SMBus Table: Output Enable Register ¹

1. A low on these bits will overide the OE# pin and force the differential output Low/Low

SMBus Table: PLL Operating Mode and Output Amplitude Control Register

Byte 1	Name	Control Function	Туре	0	1	Default
Bit 7	PLLMODERB1	PLL Mode Readback Bit 1	R	Soo PLL Operat	ing Mode Table	Latch
Bit 6	PLLMODERB0	PLL Mode Readback Bit 0	R	See PLL Operating Mode Table		Latch
Bit 5	PLLMODE_SWCNTRL	Enable SW control of PLL Mode	RW	Values in B1[7:6] set PLL Mode	Values in B1[4:3] set PLL Mode	0
Bit 4	PLLMODE1	PLL Mode Control Bit 1	RW ¹	See PLL Operating Mode Table		0
Bit 3	PLLMODE0	PLL Mode Control Bit 0	RW ¹	See FLL Operat		0
Bit 2		Reserved				1
Bit 1	AMPLITUDE 1	Controls Output Amplitude	RW	00 = 0.6V 01 = 0.7V 10= 0.8V 11 = 0.9V		1
Bit 0	AMPLITUDE 0		RW			0

1. B1[5] must be set to a 1 for these bits to have any effect on the part.

SMBus Table: DIF Slew Rate Control Register

Byte 2	Name	Control Function	Туре	0	1	Default
Bit 7		Reserved				1
Bit 6	SLEWRATESEL DIF3	Slew Rate Selection	RW	2 V/ns	3 V/ns	1
Bit 5	SLEWRATESEL DIF2	Slew Rate Selection	RW	2 V/ns	3 V/ns	1
Bit 4	Reserved					
Bit 3	SLEWRATESEL DIF1	Slew Rate Selection	RW	2 V/ns	3 V/ns	1
Bit 2		Reserved				1
Bit 1	SLEWRATESEL DIF0	Slew Rate Selection	RW	2 V/ns	3 V/ns	1
Bit 0		Reserved				1

SMBus Table: Frequency Select Control Register

Name	Control Function	Туре	0	1	Default
	Reserved				
Reserved					
FREQ_SEL_EN	Enable SW selection of frequency	RW	SW frequency change disabled		
FSEL1	Freq. Select Bit 1	RW ¹	Soo Fraguanay Salaat Tabla		0
FSEL0	Freq. Select Bit 0	RW ¹	See Trequency	V Select Table	0
	Reserved				1
	Reserved			1	
SLEWRATESEL FB	Adjust Slew Rate of FB	RW	2V/ns	3V/ns	1
	FREQ_SEL_EN FSEL1 FSEL0	Reserved Reserved FREQ_SEL_EN Enable SW selection of frequency FSEL1 Freq. Select Bit 1 FSEL0 Freq. Select Bit 0 Reserved Reserved	Reserved Reserved Reserved FREQ_SEL_EN Enable SW selection of frequency RW FSEL1 Freq. Select Bit 1 RW ¹ FSEL0 Freq. Select Bit 0 RW ¹ Reserved Reserved Reserved	Reserved Reserved Reserved FREQ_SEL_EN Enable SW selection of frequency RW SW frequency change disabled FSEL1 Freq. Select Bit 1 RW ¹ See Frequency FSEL0 Freq. Select Bit 0 RW ¹ See Frequency Reserved Reserved	Reserved Reserved Reserved FREQ_SEL_EN Enable SW selection of frequency RW SW frequency change disabled SW frequency change enabled FSEL1 Freq. Select Bit 1 RW ¹ See Frequency Select Table FSEL0 Freq. Select Bit 0 RW ¹ See Frequency Select Table Reserved Reserved

1. B3[5] must be set to a 1 for these bits to have any effect on the part.

Byte 4 is Reserved and reads back 'hFF

SMBus Table: Revision and Vendor ID Register

Byte 5	Name	Control Function	Туре	0	1	Default
Bit 7	RID3		R			0
Bit 6	RID2	Revision ID	R	A rev = 0000		0
Bit 5	RID1		R	A lev-	0	
Bit 4	RID0		R			0
Bit 3	VID3		R			0
Bit 2	VID2	VENDOR ID	R	0001	0001 = IDT	
Bit 1	VID1	VENDOR ID	R			0
Bit 0	VID0		R			1

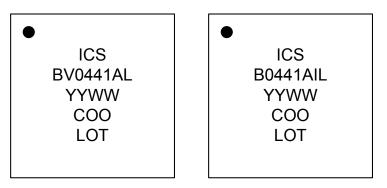
SMBus Table: Device Type/Device ID

Byte 6	Name	Control Function	Туре	0	1	Default
Bit 7	Device Type1		R	00 = FGV,	01 = DBV,	0
Bit 6	Device Type0	- Device Type	R	10 = DMV, 11= Reserved		1
Bit 5	Device ID5		R		0	
Bit 4	Device ID4		R			0
Bit 3	Device ID3	Device ID	R	000100 bina	000100 binary or 04 hex	
Bit 2	Device ID2	Device iD	R	000100 0111a		1
Bit 1	Device ID1		R			0
Bit 0	Device ID0		R			0

SMBus Table: Byte Count Register

Byte 7	Name	Control Function	Туре	0	1	Default
Bit 7		Reserved				0
Bit 6		Reserved				0
Bit 5		Reserved				0
Bit 4	BC4		RW			0
Bit 3	BC3		RW	Writing to this regist	er will configure how	1
Bit 2	BC2	Byte Count Programming	RW	many bytes will be r	ead back, default is	0
Bit 1	BC1		RW	= 8 b	ytes.	0
Bit 0	BC0		RW			0

Marking Diagrams



Notes:

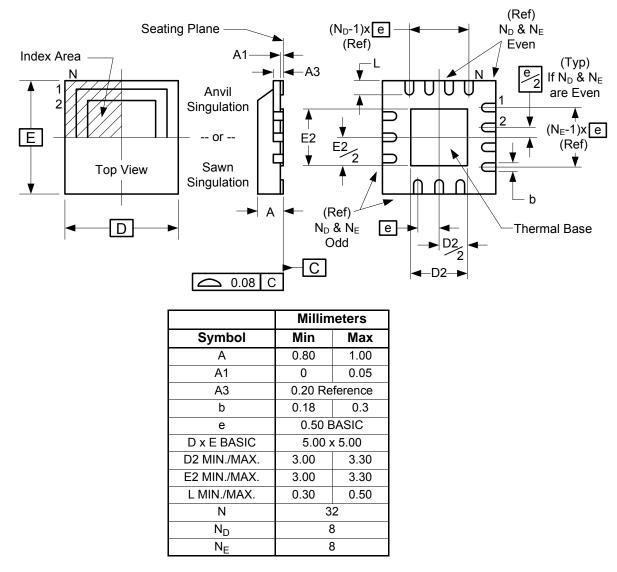
- 1. "LOT" is the lot sequence number.
- 2. "COO" denotes country of origin.
- 3. YYWW is the last two digits of the year and week that the part was assembled.
- 4. Line 2: truncated part number
- 5. "L" denotes RoHS compliant package.
- 6. "I" denotes industrial temperature range device.

Thermal Characteristics

PARAMETER	SYMBOL	CONDITIONS	PKG	TYP VALUE	UNITS	NOTES
Thermal Resistance	θ _{JC}	Junction to Case	NLG32 -	42	°C/W	1
	θ_{Jb}	Junction to Base		2.4	°C/W	1
	θ_{JA0}	Junction to Air, still air		39	°C/W	1
	θ_{JA1}	Junction to Air, 1 m/s air flow		33	°C/W	1
	θ_{JA3}	Junction to Air, 3 m/s air flow		28	°C/W	1
	θ_{JA5}	Junction to Air, 5 m/s air flow		27	°C/W	1

¹ePad soldered to board

Package Outline and Package Dimensions (NLG32)



Ordering Information

Part / Order Number Shipping Packaging		Package	Temperature	
9DBV0441AKLF	Trays	32-pin VFQFPN	0 to +70° C	
9DBV0441AKLFT	Tape and Reel	32-pin VFQFPN	0 to +70° C	
9DBV0441AKILF	Trays	32-pin VFQFPN	-40 to +85° C	
9DBV0441AKILFT	Tape and Reel	32-pin VFQFPN	-40 to +85° C	

"LF" suffix to the part number are the Pb-Free configuration and are RoHS compliant.

"A" is the device revision designator (will not correlate with the datasheet revision).

Revision History

Rev.	Initiator	Issue Date	Description	Page #
A	RDW	8/13/2012	 Removed "Differential" from DS title and Recommended Application, corrected typo's in Description. Updated block diagram to indicate internal terminations. Corrected spelling error in pullup/pulldown text under pinout Updated all electrical tables and added "Industry Limit" column to "Phase Jitter Parameters". Updated Byte3[0] to be consistent with Byte 2. Updated Byte6[7:6] definition. Added thermal data to page 12. Added NLG32 to "Package Outline and Package Dimensions" on page 13. Move to final. 	1,2,5- 8,10, 12,13
В	RDW	2/25/2013	 Changed VIH min. from 0.65*VDD to 0.75*VDD Changed VIL max. from 0.35*VDD to 0.25*VDD Added missing mid-level input voltage spec (VIM) of 0.4*VDD to 0.6*VDD. 	6
С	RDW	10/27/2014	 Updated front page text for consistency and updated block diagram resistor colors to highlight internal resistors. Updated max frequency of 100MHz PLL mode from 110MHz to 140MHz Updated max frequency of 125MHz PLL mode from 137.5MHz to 175MHz Updated max frequency of 50MHz PLL mode from 55MHz to 65MHz 	1,6
D	RDW	11/26/2014	 Updated Key Specifications with addtive phase jitter. Added additive phase jitter plot to specifications. 	1, 9-10
E	RDW	4/22/2016	 Updated max frequency of 100MHz PLL mode to 140MHz Updated max frequency of 125MHz PLL mode to 175MHz Updated max frequency of 50MHz PLL mode to 65MHz 	7



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