阅读申明

- 1.本站收集的数据手册和产品资料都来自互联网,版权归原作者所有。如读者和版权方有任何异议请及时告之,我们将妥善解决。
- 2.本站提供的中文数据手册是英文数据手册的中文翻译,其目的是协助用户阅读,该译文无法自动跟随原稿更新,同时也可能存在翻译上的不当。建议读者以英文原稿为参考以便获得更精准的信息。
- 3.本站提供的产品资料,来自厂商的技术支持或者使用者的心得体会等,其内容可能存在描 叙上的差异,建议读者做出适当判断。
- 4.如需与我们联系,请发邮件到marketing@iczoom.com,主题请标有"数据手册"字样。

Read Statement

- 1. The datasheets and other product information on the site are all from network reference or other public materials, and the copyright belongs to the original author and original published source. If readers and copyright owners have any objections, please contact us and we will deal with it in a timely manner.
- 2. The Chinese datasheets provided on the website is a Chinese translation of the English datasheets. Its purpose is for reader's learning exchange only and do not involve commercial purposes. The translation cannot be automatically updated with the original manuscript, and there may also be improper translations. Readers are advised to use the English manuscript as a reference for more accurate information.
- 3. All product information provided on the website refer to solutions from manufacturers' technical support or users the contents may have differences in description, and readers are advised to take the original article as the standard.
- 4. If you have any questions, please contact us at marketing@iczoom.com and mark the subject with "Datasheets" .



6-OUTPUT LOW-POWER HCSL BUFFER FOR PCIE GEN1-2-3 AND QPI

9ZXL0651

General Description

The 9ZXL0651 is a low-power 6-output differential buffer that meets all the performance requirements of the Intel DB1200Z specification. It consumes 50% less power than standard HCSL devices and has internal terminations to allow direct connection to 85 ohm transmission lines. The 9ZXL0651 is backwards compatible to PCIe Gen1 and Gen2 and QPI 6.4GT/s specifications. A fixed, internal feedback path maintains low drift for critical QPI applications.

Recommended Application

6-Output Low-Power HCSL Buffer for PCIe Gen1-2-3 and QPI

Output Features

 6 - 0.7V low-power HCSL (LP-HCSL) output pairs w/integrated terminations

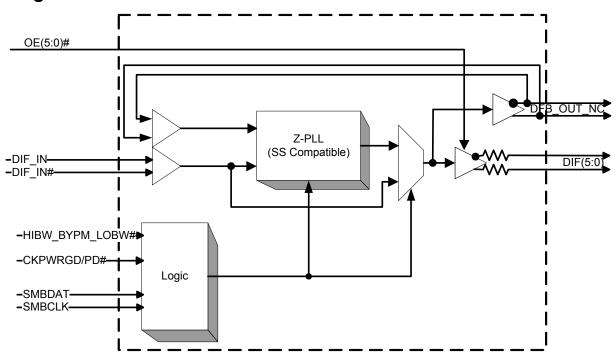
Features/Benefits

- Low-Power-HCSL outputs w/Zo = 85Ω ; save power and board space no termination resistors required. Ideal for blade servers.
- Space-saving 40-pin VFQFPN package
- Fixed feedback path for 0ps input-to-output delay
- 6 OE# pins; Hardware control of each output
- PLL or bypass mode; PLL can dejitter incoming clock
- Selectable PLL bandwidth; minimizes jitter peaking in downstream PLL's
- Spread Spectrum Compatible; tracks spreading input clock for low EMI

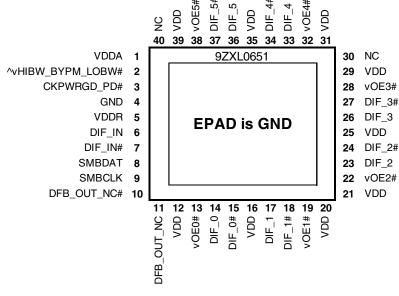
Key Specifications

- Cycle-to-cycle jitter <50ps
- Output-to-output skew <65 ps
- Input-to-output delay variation <50ps
- PCle Gen3 phase jitter <1.0ps RMS
- QPI 9.6GT/s 12UI phase jitter <0.2ps RMS

Block Diagram



Pin Configuration



40-VFQFPN

^ prefix indicates internal Pull-Up Resistor
v prefix indicates Internal Pull-Down Resistor
^v prefix indicates Internal Pull-Up/Down Resistor (biased to
VDD/2)
5mm x 5mm 0.4mm pin pitch

Power Management Table

	CKPWRGD_PD#	DIF_IN/ DIF_IN#	SMBus EN bit	DIF(5:0)/ DIF(5:0)#	PLL STATE IF NOT IN BYPASS MODE
	0	Х	Х	Low/Low	OFF
Γ	4	Dunning	0	Low/Low	ON
	ı	Running	1	Running	ON

PLL Operating Mode

HiBW_BypM_LoBW#	MODE
Low	PLL Lo BW
Mid	Bypass
High	PLL Hi BW

NOTE: PLL is OFF in Bypass Mode

Power Connections

Pin No				
VDD	Description			
1	41	Analog PLL		
5	4	Analog Input		
12,16,20,24,27	44	DIE de de		
,31,32,36,40	41	DIF clocks		

PLL Operating Mode Readback Table

HiBW_BypM_LoBW#	Byte0, bit 7	Byte 0, bit 6
Low (Low BW)	0	0
Mid (Bypass)	0	1
High (High BW)	1	1

Tri-level Input Thresholds

Level	Voltage				
Low	<0.8V				
Mid	1.2 <vin<1.8v< th=""></vin<1.8v<>				
High	Vin > 2.2V				

9ZXL0651 SMBus Address

1101100	+ Read/Write bit

Pin Descriptions

PIN#	PIN NAME	PIN TYPE	DESCRIPTION
1	VDDA	PWR	3.3V power for the PLL core.
2	^vHIBW_BYPM_LOBW#	LATCHE D IN	Trilevel input to select High BW, Bypass or Low BW mode. See PLL Operating Mode Table for Details.
		DIN	3.3V Input notifies device to sample latched inputs and start up on first high assertion, or
3	CKPWRGD_PD#	Trays	exit Power Down Mode on subsequent assertions. Low enters Power Down Mode.
4	GND	GND	Ground pin.
5	VDDR	PWR	3.3V power for differential input clock (receiver). This VDD should be treated as an analog power rail and filtered appropriately.
6	DIF_IN	IN	0.7 V Differential True input
7	DIF_IN#	IN	0.7 V Differential Complementary Input
8	SMBDAT	I/O	Data pin of SMBUS circuitry, 5V tolerant
9	SMBCLK	IN	Clock pin of SMBUS circuitry, 5V tolerant
			Complementary half of differential feedback output, provides feedback signal to the PLL
10	DFB_OUT_NC#	OUT	for synchronization with input clock to eliminate phase error. This pin should NOT be connected on the circuit board, the feedback is internal to the package.
11	DFB_OUT_NC	OUT	True half of differential feedback output, provides feedback signal to the PLL for synchronization with the input clock to eliminate phase error. This pin should NOT be connected on the circuit board, the feedback is internal to the package.
12	VDD	PWR	Power supply, nominal 3.3V
13	vOE0#	IN	Active low input for enabling DIF pair 0. This pin has an internal pull-down. 1 = disable outputs, 0 = enable outputs
14	DIF_0	OUT	0.7V differential true clock output
15	DIF_0#	OUT	0.7V differential Complementary clock output
16	VDD	PWR	Power supply, nominal 3.3V
17	DIF_1	OUT	0.7V differential true clock output
18	DIF_1#	OUT	0.7V differential Complementary clock output
19	vOE1#	IN	Active low input for enabling DIF pair 1. This pin has an internal pull-down. 1 = disable outputs, 0 = enable outputs
20	VDD	PWR	Power supply, nominal 3.3V
21	VDD	PWR	Power supply, nominal 3.3V
22	vOE2#	IN	Active low input for enabling DIF pair 2. This pin has an internal pull-down. 1 = disable outputs, 0 = enable outputs
- 00	DIF_2	OUT	
23		OUT	0.7V differential true clock output
24	DIF_2#	OUT PWR	0.7V differential Complementary clock output Power supply, nominal 3.3V
25	VDD DIF_3		
26		OUT	0.7V differential true clock output
27	DIF_3#	OUT	0.7V differential Complementary clock output Active low input for enabling DIF pair 3. This pin has an internal pull-down.
28	vOE3#	IN	1 = disable outputs, 0 = enable outputs
20	VDD	PWR	Power supply, nominal 3.3V
29	NC		No Connection.
30 31	VDD	N/A PWR	Power supply, nominal 3.3V
32	vOE4#	IN	Active low input for enabling DIF pair 4. This pin has an internal pull-down.
			1 =disable outputs, 0 = enable outputs
33	DIF_4	OUT	0.7V differential true clock output
34	DIF_4#	OUT	0.7V differential Complementary clock output
35	VDD	PWR	Power supply, nominal 3.3V
36	DIF_5	OUT	0.7V differential true clock output
37	DIF_5#	OUT	0.7V differential Complementary clock output
38	vOE5#	IN	Active low input for enabling DIF pair 5. This pin has an internal pull-down. 1 =disable outputs, 0 = enable outputs
39	VDD	PWR	Power supply, nominal 3.3V
	NC	N/A	No Connection.
41	EPAD	GND	Ground Pad.
41	LI AD	GIND	jarouna i au.

Absolute Maximum Ratings

Stresses above the ratings listed below can cause permanent damage to the 9ZXL0651. These ratings, which are standard values for IDT commercially rated parts, are stress ratings only. Functional operation of the device at these or any other conditions above those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods can affect product reliability. Electrical parameters are guaranteed only over the recommended operating temperature range.

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
	VDD, VDDA,						
3.3V Core Supply Voltage	VDDR	VDD for core logic and PLL			4.6	V	1,2
Input Low Voltage	V_{IL}		GND-0.5			V	1
Input High Voltage	V _{IH}	Except for SMBus interface			V _{DD} +0.5V	V	1
Input High Voltage	V _{IHSMB}	SMBus clock and data pins			5.5V	٧	1
Storage Temperature	Ts		-65		150	°C	1
Junction Temperature	Tj				125	°C	1
Input ESD protection	ESD prot	Human Body Model	2000			V	1

¹Guaranteed by design and characterization, not 100% tested in production.

Electrical Characteristics-Clock Input Parameters

 $T_A = T_{COM}$; Supply Voltage $V_{DD} = 3.3 \text{ V +/-5}\%$

TA COM Cappy Fortage 100 cite 1 / 2/2								
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES	
Input High Voltage - DIF_IN	V _{IHDIF}	Differential inputs (single-ended measurement)	600	800	1150	mV	1	
Input Low Voltage - DIF_IN	V_{ILDIF}	Differential inputs (single-ended measurement)	V _{SS} - 300	0	300	mV	1	
Input Common Mode Voltage - DIF_IN	V_{COM}	Common Mode Input Voltage	300		1000	mV	1	
Input Amplitude - DIF_IN	V _{SWING}	Peak to Peak value (single-ended measurement)	300		1450	mV	1	
Input Slew Rate - DIF_IN	dv/dt	Measured differentially	0.35			V/ns	1,2	
Input Leakage Current	I _{IN}	$V_{IN} = V_{DD}$, $V_{IN} = GND$	-5		5	uA	1	
Input Duty Cycle	d_{tin}	Measurement from differential wavefrom	45	50	55	%	1	
Input Jitter - Cycle to Cycle	J_{DIFIn}	Differential Measurement	0		125	ps	1	

¹ Guaranteed by design and characterization, not 100% tested in production.

² Operation under these conditions is neither implied nor guaranteed.

²Slew rate measured through +/-75mV window centered around differential zero

Electrical Characteristics-Input/Supply/Common Parameters

 $T_A = T_{COM}$; Supply Voltage $V_{DD} = 3.3 \text{ V +/-5}\%$

$I_A = I_{COM}$; Supply Voltage V	DD = 3.3 V +/-0	07/0					
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Ambient Operating Temperature	T _{COM}	Commmercial range	0	35	70	°C	1
Input High Voltage	V _{IH}	Single-ended inputs, except SMBus, low threshold and tri-level inputs	2		V _{DD} + 0.3	٧	1
Input Low Voltage	V_{IL}	Single-ended inputs, except SMBus, low threshold and tri-level inputs	GND - 0.3		0.8	V	1
	I _{IN}	Single-ended inputs, $V_{IN} = GND$, $V_{IN} = VDD$	-5		5	uA	1
Input Current	I _{INP}	$\label{eq:VIN} Single-ended inputs \\ V_{IN} = 0 \ V; \ Inputs \ with internal \ pull-up \ resistors \\ V_{IN} = \ VDD; \ Inputs \ with \ internal \ pull-down \ resistors$	-200		200	uA	1
	F _{ibyp}	V _{DD} = 3.3 V, Bypass mode	1		150	MHz	2
Input Frequency	F _{ipII}	V _{DD} = 3.3 V, 100MHz PLL mode	90	100.00	110	MHz	2
Pin Inductance	L _{pin}				7	nΗ	1
	C _{IN}	Logic Inputs, except DIF_IN	1.5		5	pF	1
Capacitance	C_{INDIF_IN}	DIF_IN differential clock inputs	1.5		2.7	pF	1,4
	C _{OUT}	Output pin capacitance			6	pF	1
Clk Stabilization	T _{STAB}	From V _{DD} Power-Up and after input clock stabilization or de-assertion of PD# to 1st clock		0.53	1	ms	1,2
Input SS Modulation Frequency	f _{MODIN}	Allowable Frequency (Triangular Modulation)	30		33	kHz	1
OE# Latency	t _{LATOE#}	DIF start after OE# assertion DIF stop after OE# deassertion	4	8	12	cycles	1,3
Tdrive_PD#	t _{DRVPD}	DIF output enable after PD# de-assertion			300	us	1,3
Tfall	t _F	Fall time of control inputs			10	ns	1,2
Trise	t _R	Rise time of control inputs			10	ns	1,2
SMBus Input Low Voltage	V_{ILSMB}				0.8	V	1
SMBus Input High Voltage	V_{IHSMB}		2.1		V_{DDSMB}	V	1
SMBus Output Low Voltage	V_{OLSMB}	@ I _{PULLUP}			0.4	V	1
SMBus Sink Current	I _{PULLUP}	@ V _{OL}	4			mA	1
Nominal Bus Voltage	V_{DDSMB}	3V to 5V +/- 10%	2.7		5.5	V	1
SCLK/SDATA Rise Time	t _{RSMB}	(Max VIL - 0.15) to (Min VIH + 0.15)			1000	ns	1
SCLK/SDATA Fall Time	t _{FSMB}	(Min VIH + 0.15) to (Max VIL - 0.15)			300	ns	1
SMBus Operating Frequency	f _{MAXSMB}	Maximum SMBus operating frequency			100	kHz	1,5

¹Guaranteed by design and characterization, not 100% tested in production.

²Control input must be monotonic from 20% to 80% of input swing.

³Time from deassertion until outputs are >200 mV

⁴DIF IN input

⁵The differential input clock must be running for the SMBus to be active

Electrical Characteristics-DIF 0.7V Low Power HCSL Outputs

 $T_A = T_{COM}$; Supply Voltage $V_{DD} = 3.3 \text{ V +/-5}\%$

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Slew rate	Trf	Scope averaging on	1	2.9	4	V/ns	1, 2, 3
Slew rate matching	ΔTrf	Slew rate matching, Scope averaging on		7	20	%	1, 2, 4
Voltage High	VHigh	Statistical measurement on single-ended signal using oscilloscope math function. (Scope	660	754	850	mV	1
Voltage Low	VLow	averaging on)		62	150] "" [1
Max Voltage	Vmax	Measurement on single ended signal using		827	1150	mV	1
Min Voltage	Vmin	absolute value. (Scope averaging off)	-300	10		IIIV	1
Vswing	Vswing	Scope averaging off	300	1395		mV	1, 2
Crossing Voltage (abs)	Vcross_abs	Scope averaging off	300	453	550	mV	1, 5
Crossing Voltage (var)	Δ-Vcross	Scope averaging off		14	140	mV	1, 6

 $^{^{1}}$ Guaranteed by design and characterization, not 100% tested in production. $C_L = 2pF$, $Z_0 = 85\Omega$ differential trace impedance).

Electrical Characteristics-Current Consumption

 $T_A = T_{COM}$; Supply Voltage $V_{DD} = 3.3 \text{ V } +/-5\%$

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
	I _{DDVDDR}	100MHz, VDDR rail		4	6	mA	1
Operating Current	I _{DDVDDAPLL}	100MHz, VDDA rail, PLL Mode		14	20	mA	1
Operating Current	I _{DDVDDABYP}	100MHz, VDDA rail, Bypass Mode		3	5	mA	1
	I _{DDVDD}	100MHz, VDD rail		41	50	mA	1
	I _{DDVDDRPD}	Power Down, VDDR Rail		3.5	5	mA	1
Powerdown Current	I _{DDVDDAPD}	Power Down, VDDA Rail		1.6	3	mA	1
	I _{DDVDDPD}	Power Down, VDD Rail		0.3	2	mA	1

¹Guaranteed by design and characterization, not 100% tested in production.

² Measured from differential waveform

³ Slew rate is measured through the Vswing voltage range centered around differential 0V. This results in a +/-150mV window around differential 0V.

⁴ Matching applies to rising edge rate for Clock and falling edge rate for Clock#. It is measured using a +/-75mV window centered on the average cross point where Clock rising meets Clock# falling. The median cross point is used to calculate the voltage thresholds the oscilloscope is to use for the edge rate calculations.

⁵ Vcross is defined as voltage where Clock = Clock# measured on a component test board and only applies to the differential rising edge (i.e. Clock rising and Clock# falling).

⁶ The total variation of all Vcross measurements in any particular system. Note that this is a subset of Vcross_min/max (Vcross absolute) allowed. The intent is to limit Vcross induced modulation by setting Δ-Vcross to be smaller than Vcross absolute.

 $^{^{2}}$ C₁ = 2pF, Zo = 85 Ω differential trace impedance

Electrical Characteristics-Skew and Differential Jitter Parameters

 $T_A = T_{COM}$; Supply Voltage $V_{DD} = 3.3 \text{ V +/-5}\%$

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
CLK_IN, DIF[x:0]	t _{SPO_PLL}	In-to-Out Skew in PLL mode @ 100MHz nominal value @35°C, 3.3V	-100	53	100	ps	1,2,4,5,8
CLK_IN, DIF[x:0]	t _{PD_BYP}	In-to-Out Skew in Bypass mode @ 100MHz nominal value @ 35°C, 3.3V	2.5	3.4	4.5	ns	1,2,3,5,8
CLK_IN, DIF[x:0]	t _{DSPO_PLL}	In-to-Out Skew Varation in PLL mode across voltage and temperature	-50	0	50	ps	1,2,3,5,8
CLK_IN, DIF[x:0]	t _{DSPO_BYP}	In-to-Out Skew Varation in Bypass mode across voltage and temperature	-250	0	250	ps	1,2,3,5,8
CLK_IN, DIF[x:0]	t _{DTE}	Random Differential Tracking error beween two 9ZX devices in Hi BW Mode		3	5	ps (rms)	1,2,3,5,8
CLK_IN, DIF[x:0]	t _{DSSTE}	Random Differential Spread Spectrum Tracking error beween two 9ZX devices in Hi BW Mode		15	75	ps	1,2,3,5,8
DIF{x:0]	t _{SKEW_ALL}	Output-to-Output Skew across all outputs (Common to Bypass and PLL mode)		39	65	ps	1,2,3,8
PLL Jitter Peaking	j _{peak-hibw}	LOBW#_BYPASS_HIBW = 1			2.5	dB	7,8
PLL Jitter Peaking	j _{peak-lobw}	LOBW#_BYPASS_HIBW = 0			2	dB	7,8
PLL Bandwidth	pll _{HIBW}	LOBW#_BYPASS_HIBW = 1			4	MHz	8,9
PLL Bandwidth	pll _{LOBW}	LOBW#_BYPASS_HIBW = 0			1.4	MHz	8,9
Duty Cycle	t _{DC}	Measured differentially, PLL Mode	45	50.1	55	%	1
Duty Cycle Distortion	t _{DCD}	Measured differentially, Bypass Mode @100MHz		-1.7	121	%	1,10
Jitter, Cycle to cycle	tions one	PLL mode		14	50	ps	1,11
Sitter, Cybic to Cybic	t _{jcyc-cyc}	Additive Jitter in Bypass Mode		0	25	ps	1,11

Notes for preceding table:

 $^{^{1}}$ C_L = 2pF, Zo = 85 Ω differential trace impedance. Input to output skew is measured at the first output edge following the corresponding input.

² Measured from differential cross-point to differential cross-point. This parameter can be tuned with external feedback path, if present.

³ All Bypass Mode Input-to-Output specs refer to the timing between an input edge and the specific output edge created by it.

⁴ This parameter is deterministic for a given device

⁵ Measured with scope averaging on to find mean value.

⁶.t is the period of the input clock

⁷ Measured as maximum pass band gain. At frequencies within the loop BW, highest point of magnification is called PLL jitter peaking.

^{8.} Guaranteed by design and characterization, not 100% tested in production.

⁹ Measured at 3 db down or half power point.

¹⁰ Duty cycle distortion is the difference in duty cycle between the output and the input clock when the device is operated in bypass mode.

¹¹ Measured from differential waveform

Electrical Characteristics-Phase Jitter Parameters

 $T_A = T_{COM}$; Supply Voltage $V_{DD} = 3.3 \text{ V +/-5}\%$

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	INDUSTRY LIMIT	UNITS	Notes
TATOMINETER	t _{jphPCleG1}	PCIe Gen 1	101114	43	46	86	ps (p-p)	1,2,3
		PCIe Gen 2 Lo Band 10kHz < f < 1.5MHz		1.4	1.5	3	ps (rms)	1,2
	t _{jphPCleG2}	PCIe Gen 2 High Band 1.5MHz < f < Nyquist (50MHz)		2.4	2.7	3.1	ps (rms)	1,2
	t _{jphPCleG3}	PCIe Gen 3 (PLL BW of 2-4MHz, 2-5MHz, CDR = 10MHz)		0.56	0.61	1	ps (rms)	1,2,4
Phase Jitter, PLL Mode	t _{jphQPI_SMI}	QPI & SMI (PLL BW of 17.04MHz 100/133MHz, 4.8Gb/s, 6.4Gb/s 12UI)		0.27	0.51	1	ps (rms)	1,5
		QPI & SMI (PLL BW of 7.8MHz 100/133MHz, 4.8Gb/s, 6.4Gb/s 12UI)		0.22	0.49	0.5	ps (rms)	1,5
		QPI & SMI (100MHz, 8.0Gb/s, 12UI)		0.16	0.28	0.3	ps (rms)	1,5
		QPI & SMI (100MHz, 9.6Gb/s, 12UI)		0.11	0.17	0.2	ps (rms)	1,5
	t _{jphPCleG1}	PCle Gen 1		1	5	N/A	ps (p-p)	1,2,3
	t _{jphPCleG2}	PCIe Gen 2 Lo Band 10kHz < f < 1.5MHz		0.0	0.0	N/A	ps (rms)	1,2,6
		PCIe Gen 2 High Band 1.5MHz < f < Nyquist (50MHz)		0.0	0.0	N/A	ps (rms)	1,2,6
	t _{jphPCleG3}	PCIe Gen 3 (PLL BW of 2-4MHz, 2-5MHz, CDR = 10MHz)		0.0	0.0	N/A	ps (rms)	1,2,4,6
Additive Phase Jitter, Bypass mode		QPI & SMI (PLL BW of 17.04MHz 100/133MHz, 4.8Gb/s, 6.4Gb/s 12UI)		0.25	0.3	N/A	ps (rms)	1,5,6
	t _{jphQPI_SMI}	QPI & SMI (PLL BW of 7.8MHz 100/133MHz, 4.8Gb/s, 6.4Gb/s 12UI)		0.10	0.15	N/A	ps (rms)	1,5,6
		QPI & SMI (100MHz, 8.0Gb/s, 12UI)		0.0	0.0	N/A	ps (rms)	1,5,6
		QPI & SMI (100MHz, 9.6Gb/s, 12UI)		0.0	0.0	N/A	ps (rms)	1,5,6

¹ Applies to all outputs.

² See http://www.pcisig.com for complete specs

³ Sample size of at least 100K cycles. This figures extrapolates to 108ps pk-pk @ 1M cycles for a BER of 1-12.

⁴ Subject to final ratification by PCI SIG.

⁵ Calculated from Intel-supplied Clock Jitter Tool

⁶ For RMS figures, additive jitter is calculated by solving the following equation: (Additive jitter)^2 = (total jittler)^2 - (input jitter)^2

Clock Periods-Differential Outputs with Spread Spectrum Disabled

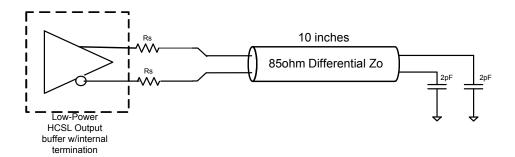
			Measurement Window							
	Center	1 Clock	1us	0.1s	0.1s	0.1s	1us	1 Clock		
SSC OFF	Freq. MHz	-c2c jitter AbsPer Min	-SSC Short-Term Average Min	- ppm Long-Term Average Min	0 ppm Period Nominal	+ ppm Long-Term Average Max	+SSC Short-Term Average Max	+c2c jitter AbsPer Max	Units	Notes
DIF	100.00	9.94900		9.99900	10.00000	10.00100		10.05100	ns	1,2,3

Clock Periods-Differential Outputs with Spread Spectrum Enabled

October			Measurement Window							
	Center	1 Clock	1us	0.1s	0.1s	0.1s	1us	1 Clock		
SSC ON	Freq. MHz	-c2c jitter AbsPer Min	-SSC Short-Term Average Min	- ppm Long-Term Average Min	0 ppm Period Nominal	+ ppm Long-Term Average Max	+SSC Short-Term Average Max	+c2c jitter AbsPer Max	Units	Notes
DIF	99.75	9.94906	9.99906	10.02406	10.02506	10.02607	10.05107	10.10107	ns	1,2,3

Notes:

Test Loads



Differential Output Terminations

DIF Zo (Ω)	Rs (Ω)
100	7
85	0

Note: No resistors are required for connection to 85ohm transmission lines.

¹Guaranteed by design and characterization, not 100% tested in production.

² All Long Term Accuracy specifications are guaranteed with the assumption that the input clock complies with CK420BQ/CK410B+ accuracy requirements (+/-100ppm). The 9ZXL0651 itself does not contribute to ppm error.

³ Driven by SRC output of main clock, 100 MHz PLL Mode or Bypass mode

General SMBus Serial Interface Information for 9ZXL0651

How to Write

- · Controller (host) sends a start bit
- Controller (host) sends the write address
- IDT clock will acknowledge
- Controller (host) sends the beginning byte location = N
- IDT clock will acknowledge
- Controller (host) sends the byte count = X
- IDT clock will acknowledge
- Controller (host) starts sending Byte N through Byte N+X-1
- IDT clock will acknowledge each byte one at a time
- Controller (host) sends a Stop bit

	Index Bl	ock '	Write Operation
Controll	er (Host)		IDT (Slave/Receiver)
Т	starT bit		
Slave A	Address		
WR	WRite		
			ACK
Beginning	g Byte = N		
			ACK
Data Byte	Count = X		
			ACK
Beginnin	g Byte N		
			ACK
0		×	
0		X Byte	0
0		ė	0
			0
Byte N	Byte N + X - 1		
			ACK
Р	stoP bit		

How to Read

- · Controller (host) will send a start bit
- Controller (host) sends the write address
- IDT clock will acknowledge
- Controller (host) sends the beginning byte location = N
- IDT clock will acknowledge
- Controller (host) will send a separate start bit
- Controller (host) sends the read address
- IDT clock will acknowledge
- IDT clock will send the data byte count = X
- IDT clock sends Byte N+X-1
- IDT clock sends Byte 0 through Byte X (if X_(H) was written to Byte 8)
- Controller (host) will need to acknowledge each byte
- Controller (host) will send a not acknowledge bit
- · Controller (host) will send a stop bit

	Index Block F	Read O	peration
Cor	ntroller (Host)		IDT (Slave/Receiver)
Т	starT bit		
SI	ave Address		
WR	WRite		
			ACK
Begi	nning Byte = N		
			ACK
RT	Repeat starT		
SI	ave Address		
RD	ReaD		
			ACK
			Data Byte Count=X
	ACK		
			Beginning Byte N
	ACK		
		<u>e</u>	0
	0	X Byte	0
	0	×	0
	0		
			Byte N + X - 1
N	Not acknowledge		
Р	stoP bit		

SMBusTable: PLL Mode, and Frequency Select Register

Byte	0 Pin#	Name	Control Function	Type	0	1	Default	
Bit 7	2	PLL Mode 1	PLL Operating Mode Rd back 1	R	See PLL Op	See PLL Operating Mode		
Bit 6	2	PLL Mode 0	PLL Operating Mode Rd back 0	R	Readback Table		Latch	
Bit 5			Reserved				0	
Bit 4			Reserved					
Bit 3		PLL_SW_EN	Enable S/W control of PLL BW	RW	HW Latch	SMBus Control	0	
Bit 2		PLL Mode 1	PLL Operating Mode 1	RW	See PLL Op	erating Mode	1	
Bit 1		PLL Mode 0	PLL Operating Mode 1	RW	Readback Table		1	
Bit 0			Reserved				1	

Note: Setting bit 3 to '1' allows the user to overide the Latch value from pin 5 via use of bits 2 and 1. Use the values from the PLL Operating Mode Readback Table. Note that Bits 7 and 6 will keep the value originally latched on pin 5. A warm reset of the system will have to accomplished if the user changes these bits.

SMBusTable: Output Control Register

Byte	e 1 Pin#	Pin # Name	Control Function	Type	0	1	Default
Bit 7			Reserved				1
Bit 6	26/27	/27 DIF_3_En	Output Control - '0' overrides OE# pin	RW	Low/Low	Enable	1
Bit 5	23/24	/24 DIF_2_En	Output Control - '0' overrides OE# pin	RW	LOW/LOW	Enable	1
Bit 4			Reserved				
Bit 3			Reserved				1
Bit 2	17/18	/18 DIF_1_En	Output Control - '0' overrides OE# pin	RW	Low/Low	Enoble	1
Bit 1	14/15	/15 DIF_0_En	Output Control - '0' overrides OE# pin	RW	Low/Low	Enable	1
Bit 0			Reserved				1

SMBusTable: Output Control Register

Byte	e 2	Pin #	Name	Control Function	Type	0	1	Default	
Bit 7				Reserved				0	
Bit 6				Reserved				0	
Bit 5				Reserved					
Bit 4				Reserved					
Bit 3				Reserved				1	
Bit 2	3	6/37	DIF_5_En	Output Control - '0' overrides OE# pin	RW	Low/Low	Enable	1	
Bit 1	3	3/34	DIF_4_En	Output Control - '0' overrides OE# pin	RW	Low/Low	Enable	1	
Bit 0				Reserved				1	

SMBusTable: Reserved Register

Byte	3	Pin #	Name	Control Function	Type	0	1	Default		
Bit 7				Reserved				0		
Bit 6				Reserved						
Bit 5				Reserved						
Bit 4				Reserved						
Bit 3				Reserved				0		
Bit 2				Reserved						
Bit 1				Reserved						
Bit 0				Reserved				0		

SMBusTable: Reserved Register

Byte	4	Pin #	Name	Control Function	Туре	0	1	Default	
Bit 7				Reserved				0	
Bit 6				Reserved				0	
Bit 5				Reserved				0	
Bit 4				Reserved					
Bit 3				Reserved				0	
Bit 2				Reserved				0	
Bit 1				Reserved				0	
Bit 0				Reserved				0	

11

SMBusTable: Vendor & Revision ID Register

Byte	5 Pin #	Name	Control Function	Type	0	1	Default
Bit 7	-	RID3		R	A rev = 0000		Х
Bit 6	-	RID2	REVISION ID	R			X
Bit 5		RID1	REVISION ID	R			Х
Bit 4	-	RID0		R			Χ
Bit 3	-	VID3		R	-	-	0
Bit 2	-	VID2	VENDOR ID	R	-	-	0
Bit 1	-	VID1		R	-	-	0
Bit 0	-	VID0		R	-	-	1

SMBusTable: DEVICE ID

Byte 6	Pin #	Name	Control Function	Type	0	1	Default
Bit 7		De	evice ID 7 (MSB)	R		•	1
Bit 6			Device ID 6	R			1
Bit 5	1		Device ID 5	R			1
Bit 4	-		Device ID 4	R		Hex	1
Bit 3	-		Device ID 3	R	l LD	пех	1
Bit 2	-		Device ID 2	R			0
Bit 1	-		Device ID 1	R			1
Bit 0	-		Device ID 0	R			1

SMBusTable: Byte Count Register

Byte	e 7 Pin#	Name	Control Function	Type	0	1	Default	
Bit 7			Reserved				0	
Bit 6			Reserved					
Bit 5			Reserved					
Bit 4	ı	BC4		RW			0	
Bit 3	ı	BC3	Writing to this register configures how	RW	Default value	is 8 hex, so 9	1	
Bit 2		BC2		RW	bytes (0 to 8) v	vill be read back	0	
Bit 1	ı	BC1	many bytes will be read back.	RW	by de	efault.	0	
Bit 0	-	BC0		RW]		0	

SMBusTable: Reserved Register

Byte	e 8	Pin #	Name	Control Function	Type	0	1	Default
Bit 7				Reserved				0
Bit 6				Reserved				0
Bit 5				Reserved				0
Bit 4				Reserved				0
Bit 3				Reserved				0
Bit 2				Reserved				0
Bit 1				Reserved				0
Bit 0				Reserved				0

Marking Diagram

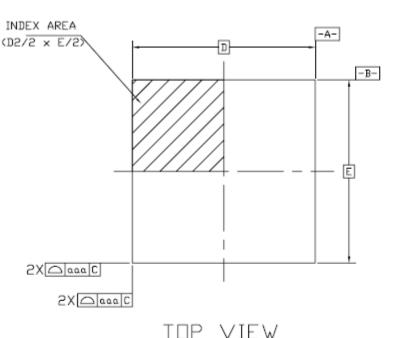


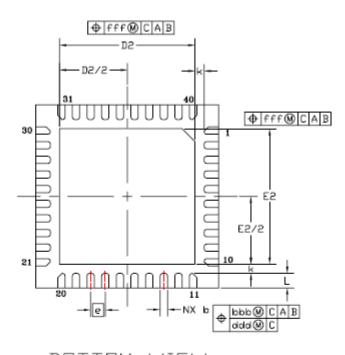
Notes:

- 1. "L" denotes RoHS compliant package.
- 2. 'LOT' denotes the lot number.
- 3. "COO": country of origin.
- 4. YYWW is the last two digits of the year and week that the part was assembled.

Package Outline and Package Dimensions (NDG40)

Package dimensions are kept current with JEDEC Publication No. 95

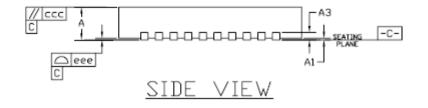




	Р_	V	1	E	W	

$B\square$	$ \sqcup M$	VIEW

SYMBOL	DIMENSION				
٢	MIN	MIN NOM			
Ь	0.15	0.20	0.25		
D	5	.00 BSC			
Ε	5.00 BSC				
D2	3.40 3.50		3.60		
E2	3.40	3.50	3.60		
L	0.30	0.40	0.50		
е	0.40 BSC				
N	40				
ND	10 (note 3)				
NE		10 (n	ote 3)		
Α	0.80		1.00		
A1	0.00	0.02	0.05		
A3		0.2 REF			
k		0.35			
aaa	0.10				
bbb	0.07				
CCC	0.10				
ddd	0.05				
eee	0.08				
fff		0.10			



NOTES:

- ALL DIMENSIONING AND TOLERANCING CONFORM TO ANSI Y14.5M-1982
- 2 ALL DIMENSIONS ARE IN MILLIMETERS.
- ND AND NE REFER TO THE NUMBER OF TERMINALS ON EACH D AND E SIDE RESPECTIVELY.

Ordering Information

Part / Order Number	Shipping Package	Package	Temperature	
9ZXL0651AKLF	Trays	40-pin VFQFPN	0 to +70°C	
9ZXL0651AKLFT	Tape and Reel	40-pin VFQFPN	0 to +70°C	

[&]quot;LF" suffix to the part number denotes Pb-Free configuration, RoHS compliant.

While the information presented herein has been checked for both accuracy and reliability, Integrated Device Technology (IDT) assumes no responsibility for either its use or for the infringement of any patents or other rights of third parties, which would result from its use. No other circuits, patents, or licenses are implied. This product is intended for use in normal commercial applications. Any other applications such as those requiring extended temperature range, high reliability, or other extraordinary environmental requirements are not recommended without additional processing by IDT. IDT reserves the right to change any circuitry or specifications without notice. IDT does not authorize or warrant any IDT product for use in life support devices or critical medical instruments.

[&]quot;A" is the device revision designator (will not correlate with the datasheet revision).

Revision History

Rev.	Issue Date	Issuer	Description	Page #
Α	10/31/2013	RDW	Updated Electrical Tables with characterization data and moved to final.	Various
В	11/25/2014		Updates to Byte 6, bits 7:4; default should be "1". Updated device ID in Byte 6 from "8B" to "FB".	12
С	3/30/2015	I KDW	1. Corrected Test Loads to remove references to IREF and Rp. These are not present on parts that have LP-HCSL outputs.	9

Innovate with IDT and accelerate your future networks. Contact:

www.IDT.com

For Sales

800-345-7015 408-284-8200 Fax: 408-284-2775 For Tech Support

www.idt.com/go/clockhelp pcclockhelp@idt.com

Corporate Headquarters

Integrated Device Technology, Inc. www.idt.com

