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200 MHz Clock Generator PLL

ADF4001

FEATURES

200 MHz Bandwidth
2.7 V to 5.5 V Power Supply
Separate Charge Pump Supply (V_P) Allows Extended Tuning Voltage in 5 V Systems
Programmable Charge Pump Currents
3-Wire Serial Interface
Hardware and Software Power-Down Mode
Analog and Digital Lock Detect
Hardware Compatible to the ADF4110/ADF4111/ ADF4112/ADF4113
Typical Operating Current 4.5 mA
Ultralow Phase Noise
16-Lead TSSOP
20-Lead LFCSP

APPLICATIONS Clock Generation Low Frequency PLLs Low Jitter Clock Source Clock Smoothing Frequency Translation SONET, ATM, ADM, DSLAM, SDM

GENERAL DESCRIPTION

The ADF4001 clock generator can be used to implement clock sources for PLLs that require very low noise, stable reference signals. It consists of a low noise digital PFD (phase frequency detector), a precision charge pump, a programmable reference divider, and a programmable 13-bit N counter. In addition, the 14-bit reference counter (R counter) allows selectable REF_{IN} frequencies at the PFD input. A complete PLL (phase-locked loop) can be implemented if the synthesizer is used with an external loop filter and VCO (voltage controlled oscillator) or VCXO (voltage controlled crystal oscillator). The N minimum value of 1 allows flexibility in clock generation.



FUNCTIONAL BLOCK DIAGRAM

REV.B

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ADF4001* PRODUCT PAGE QUICK LINKS

Last Content Update: 02/23/2017

COMPARABLE PARTS

View a parametric search of comparable parts.

EVALUATION KITS

ADF4001 Evaluation Board

DOCUMENTATION

Application Notes

- AN-30: Ask the Applications Engineer PLL Synthesizers
- AN-873: Lock Detect on the ADF4xxx Family of PLL Synthesizers

Data Sheet

ADF4001: 200 MHz Clock Generator PLL Data Sheet

User Guides

- UG-092: The PLL Frequency Synthesizer Evaluation Board for the ADF4001
- UG-476: PLL Software Installation Guide

SOFTWARE AND SYSTEMS REQUIREMENTS 🖵

- ADF4001 FMC-SDP Interposer & Evaluation Board / Xilinx KC705 Reference Design
- BeMicro FPGA Project for ADF4001 with Nios driver

TOOLS AND SIMULATIONS \square

- ADIsimPLL[™]
- ADIsimRF

REFERENCE MATERIALS

Technical Articles

- Phase Locked Loops for High-Frequency Receivers and Transmitters – Part 1
- Phase Locked Loops for High-Frequency Receivers and Transmitters – Part 3
- Phase-Locked Loops for High-Frequency Receivers and Transmitters - Part 2

DESIGN RESOURCES

- ADF4001 Material Declaration
- PCN-PDN Information
- Quality And Reliability
- Symbols and Footprints

DISCUSSIONS

View all ADF4001 EngineerZone Discussions.

SAMPLE AND BUY

Visit the product page to see pricing options.

TECHNICAL SUPPORT

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DOCUMENT FEEDBACK 🖵

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 $\begin{array}{l} \textbf{ADF4001-SPECIFICATIONS}^{1} \\ \textbf{CPGND} = 0 \ \textbf{V}; \ \textbf{R}_{\text{SET}} = 4.7 \ \textbf{k} \Omega; \ \textbf{T}_{\text{A}} = \textbf{T}_{\text{MIN}} \ \textbf{to} \ \textbf{T}_{\text{MAX}}, \ \textbf{unless otherwise noted}; \ \textbf{dBm referred to 50} \ \Omega.) \end{array} \\ \end{array}$

Parameter	B Version	Unit	Test Conditions/Comments						
RF CHARACTERISTICS (3 V) RF Input Frequency RF Input Sensitivity	5/165 -10/0	MHz min/max dBm min/max	See Figure 3 for Input Circuit						
RF CHARACTERISTICS (5 V) RF Input Frequency	10/200 20/200	MHz min/max MHz min/max	-5/0 dBm min/max -10/0 dBm min/max						
REF _{IN} CHARACTERISTICS REF _{IN} Input Frequency	5/104	MHz min/max	See Figure 2 for Input Circuit For f < 5 MHz, Use DC-Coupled Square Wave (0 to V _{DD})						
REF _{IN} Input Sensitivity ²	-5	dBm min	AC-Coupled. When DC-Coupled: 0 to V _{DD} Max (CMOS Compatible)						
REF _{IN} Input Capacitance REF _{IN} Input Current	10 ±100	pF max µA max							
PHASE DETECTOR Phase Detector Frequency ³	55	MHz max							
$\begin{array}{c} CHARGE PUMP \\ I_{CP} Sink/Source \\ High Value \\ Low Value \\ Absolute Accuracy \\ R_{SET} Range \\ I_{CP} Three-State Leakage Current \\ Sink and Source Current Matching \\ I_{CP} vs. V_{CP} \\ I_{CP} vs. Temperature \end{array}$	5 625 2.5 2.7/10 1 2 1.5 2	mA typ μA typ % typ kΩ typ nA typ % typ % typ % typ	$\begin{array}{l} Programmable: See Table V\\ With R_{SET} = 4.7 \ k\Omega\\ With R_{SET} = 4.7 \ k\Omega\\ See Table V\\ 0.5 \ V \leq V_{CP} \leq V_P - 0.5\\ 0.5 \ V \leq V_{CP} \leq V_P - 0.5\\ V_{CP} = V_P/2 \end{array}$						
LOGIC INPUTS V _{INH} , Input High Voltage V _{INL} , Input Low Voltage I _{INH} /I _{INL} , Input Current C _{IN} , Input Capacitance	$\begin{array}{c} 0.8 \times DV_{DD} \\ 0.2 \times DV_{DD} \\ \pm 1 \\ 10 \end{array}$	V min V max μA max pF max							
LOGIC OUTPUTS V _{OH} , Output High Voltage V _{OL} , Output Low Voltage	$\begin{array}{c} DV_{DD}-0.4\\ 0.4 \end{array}$	V min V max	$I_{OH} = 500 \ \mu A$ $I_{OL} = 500 \ \mu A$						
POWER SUPPLIES AV_{DD} DV_{DD} V_P I_{DD}^4 (AI_{DD} + DI_{DD}) $ADF4001$ I_P Low Power Sleep Mode	2.7/5.5 AV _{DD} AV _{DD} /6.0 5.5 0.4 1	V min/V max V min/V max mA max mA max µA typ	$AV_{DD} \le V_P \le 6.0 V$ 4.5 mA typical $T_A = 25^{\circ}C$						
NOISE CHARACTERISTICS ADF4001 Phase Noise Floor ⁵ Phase Noise Performance ⁶ 200 MHz Output ⁷	-161 -153 -99	dBc/Hz typ dBc/Hz typ dBc/Hz typ	 @ 200 kHz PFD Frequency @ 1 MHz PFD Frequency @ VCXO Output @ 1 kHz Offset and 200 kHz PFD Frequency 						
Spurious Signals 200 MHz Output ⁷	-90/-95	dBc typ/dBc typ	@ 200 kHz/400 kHz and 200 kHz PFD Frequency						

NOTES

¹Operating temperature range (B Version) is -40°C to +85°C.

 ${}^{2}AV_{DD} = DV_{DD} = 3 V$; for $AV_{DD} = DV_{DD} = 5 V$, use CMOS compatible levels.

³Guaranteed by design. Sample tested to ensure compliance.

 ${}^{4}T_{A} = 25^{\circ}C$; $AV_{DD} = DV_{DD} = 3 V$; $RF_{IN} = 100 MHz$.

⁵The synthesizer phase noise floor is estimated by measuring the in-band phase noise at the output of the VCO and subtracting 20 logN (where N is the N divider value).

⁶The phase noise is measured with the EVAL-ADF4001EB1 evaluation board and the HP8562E spectrum analyzer.

 ${}^{7}f_{REF_{IN}} = 10 \text{ MHz}; f_{PFD} = 200 \text{ kHz}; \text{ Offset Frequency} = 1 \text{ kHz}; f_{RF} = 200 \text{ MHz}; \text{ N} = 1000; \text{ Loop B/W} = 20 \text{ kHz}.$

Specifications subject to change without notice.

TIMING CHARACTERISTICS (AV_{DD} = DV_{DD} = 3 V ± 10%, 5 V ± 10%; AV_{DD} \leq V_P \leq 6.0 V; AGND = DGND = CPGND = 0 V; R_{SET} = 4.7 k\Omega; T_A = T_{MIN} to T_{MAX}, unless otherwise noted; dBm referred to 50 Ω .)

Parameter	Limit at T _{MIN} to T _{MAX} (B Version)	Unit	Test Conditions/Comments
t ₁	10	ns min	DATA to CLOCK Setup Time
t ₂	10	ns min	DATA to CLOCK Hold Time
t ₃	25	ns min	CLOCK High Duration
t ₄	25	ns min	CLOCK Low Duration
t ₅	10	ns min	CLOCK to LE Setup Time
t ₆	20	ns min	LE Pulsewidth

Guaranteed by design but not production tested.

Specifications subject to change without notice.



Figure 1. Timing Diagram

ABSOLUTE MAXIMUM RATINGS^{1, 2}

(T_A = 25°C, unless otherwise noted.)

TSSOP θ_{IA} Thermal Impedance	150.4°C/W
LFCSP θ_{IA} Thermal Impedance (Paddle Soldered)	122°C/W
LFCSP θ_{IA} Thermal Impedance (Paddle Not Soldered	l) 216°C/W
Lead Temperature, Soldering	
	01 50 0

Vapor Phase (60 s	sec)	• •	•	• •	•	• •	•	•	 •	• •	•	• •	•	•	 •	• •	215°C
Infrared (15 sec)							•		 •			• •	• •			•••	220°C

NOTES

¹Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those listed in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

²This device is a high performance RF integrated circuit with an ESD rating of $<2 \,k\Omega$ and it is ESD sensitive. Proper precautions should be taken for handling and assembly.

 3 GND = AGND = DGND = 0 V.

CAUTION_

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although the ADF4001 features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.



PIN CONFIGURATIONS 20 CP 19 R_{SET} 18 V_P 17 DV_{DD} 16 DV_{DD} 16 V_P 15 DV_{DD} R_{SET} 1 CP 2 14 MUXOUT CPGND 3 15 MUXOUT 14 LE CPGND 1 AGND 4 ADF4001 13 LE AGND 2 ADF4001 TOP VIEW (Not to Scale) TOP VIEW (Not to Scale) 12 DATA 11 CLK 10 CE RF_{IN}B 5 AGND 3 13 DATA RF_{IN}A 6 RF_{IN}B 4 12 CLK RF_{IN}A 5 11 CE AV_{DD} 7 REFIN 8 9 DGND AV_{DD} 6 AV_{DD} 7 AV_{DD} 8 REF_{IN} 9 DGND 9 DGND 10 NOTES 1. TRANSISTOR COUNT 6425 (CMOS) AND 50 (BIPOLAR). 02569-003 NOTES 1. TRANSISTOR COUNT 6425 (CMOS) AND 50 (BIPOLAR). 2. CONNECT EXPOSED PAD TO AGND. 2569.00. LFCSP TSSOP

Table 1	. Pin	Function	Descri	ptions
14010 1		I willettoll	Deseri	P 110 110

TSSOP	LFCSP	_	
Pin No.	Pin No.	Mnemonic	Description
1	19	Rset	Connecting a resistor between this pin and CPGND sets the maximum charge pump output current. The nominal voltage potential at the R_{SET} pin is 0.66 V. The relationship between I_{CP} and R_{SET} is 23.5
			$I_{CP MAX} = \frac{1}{R_{SET}}$
_			So, with $R_{\text{SET}} = 4.7 \text{ k}\Omega$, $I_{\text{CP MAX}} = 5 \text{ mA}$.
2	20	СР	Charge Pump Output. When enabled, this provides $\pm I_{CP}$ to the external loop filter which, in turn, drives the external VCO or VCXO.
3	1	CPGND	Charge Pump Ground. This is the ground return path for the charge pump.
4	2, 3	AGND	Analog Ground. This is the ground return path of the prescaler.
5	4	RF _{IN} B	Complementary Input to the N counter. This point must be decoupled to the ground plane with a small bypass capacitor, typically 100 pF. See Figure 3.
6	5	RFINA	Input to the N counter. This small signal input is ac-coupled to the external VCO or VCXO.
7	6, 7	AV _{DD}	Analog Power Supply. This ranges from 2.7 V to 5.5 V. Decoupling capacitors to the analog ground plane should be placed as close as possible to this pin. AV_{DD} must have the same value as DV_{DD} .
8	8	REF _{IN}	Reference Input. This is a CMOS input with a nominal threshold of $V_{DD}/2$ and a dc equivalent input resistance of 100 k Ω . See Figure 2. This input can be driven from a TTL or CMOS crystal oscillator or can be ac-coupled.
9	9, 10	DGND	Digital Ground.
10	11	CE	Chip Enable. A logic low on this pin powers down the device and puts the charge pump output into three-state mode. Taking the pin high will power up the device, depending on the status of the power-down bit F2.
11	12	CLK	Serial Clock Input. This serial clock is used to clock in the serial data to the registers. The data is latched into the 24-bit shift register on the CLK rising edge. This input is a high impedance CMOS input.
12	13	DATA	Serial Data Input. The serial data is loaded MSB first with the two LSBs being the control bits. This input is a high impedance CMOS input.
13	14	LE	Load Enable, CMOS Input. When LE goes high, the data stored in the shift registers is loaded into one of the four latches, the latch being selected by using the control bits.
14	15	MUXOUT	This multiplexer output allows either the lock detect, the scaled RF, or the scaled reference frequency to be accessed externally.
15	16, 17	DV _{DD}	Digital Power Supply. This ranges from 2.7 V to 5.5 V. Decoupling capacitors to the digital ground plane should be placed as close as possible to this pin. DV_{DD} must be the same value as AV_{DD} .
16	18	VP	Charge Pump Power Supply. This should be greater than or equal to V_{DD} . In systems where V_{DD} is 3 V, it can be set to 5 V and used to drive a VCO or VCXO with a tuning range of up to 5 V.
N/A	EP	EPAD	Exposed Pad. The exposed pad should be connected to AGND.

Typical Performance Characteristics-ADF4001



TPC 1. Input Sensitivity, V_{DD} = 3.3 V, 100 pF on RF_{IN}



TPC 2. Input Sensitivity, $V_{DD} = 3.3 V$, 100 pF on RF_{IN}



TPC 3. Phase Noise (200 MHz, 200 kHz, 20 kHz)



TPC 4. Integrated Phase Noise (200 MHz, 200 kHz, 20 kHz)



TPC 5. Reference Spurs (200 MHz, 200 kHz, 20 kHz)

CIRCUIT DESCRIPTION

Reference Input Section

The reference input stage is shown in Figure 2. SW1 and SW2 are normally closed switches. SW3 is normally open. When power-down is initiated, SW3 is closed and SW1 and SW2 are opened. This ensures that there is no loading of the REF_{IN} pin on power-down.



Figure 2. Reference Input Stage

RF Input Stage

The RF input stage is shown in Figure 3. It is followed by a two-stage limiting amplifier to generate the CML clock levels needed for the N counter buffer.



Figure 3. RF Input Stage

N Counter

The N CMOS counter allows a wide ranging division ratio in the PLL feedback counter. Division ratios of 1 to 8191 are allowed.

N and R Relationship

The N counter with the R counter make it possible to generate output frequencies that are spaced only by the reference frequency divided by R. The equation for the VCO frequency is

$$f_{VCO} = N/R \times f_{REFIN}$$

 f_{VCO} is the output frequency of the external voltage cotrolled oscillator (VCO).

N is the preset divide ratio of the binary 13-bit counter (1 to 8,191).

 f_{REFIN} is the external reference frequency oscillator.

R is the preset divide ratio of the binary 14-bit programmable reference counter (1 to 16,383).



Figure 4. N Counter

R Counter

The 14-bit R counter allows the input reference frequency to be divided down to produce the reference clock to the phase frequency detector (PFD). Division ratios from 1 to 16,383 are allowed.

PHASE FREQUENCY DETECTOR (PFD) AND CHARGE PUMP

The PFD takes inputs from the R counter and N counter and produces an output proportional to the phase and frequency difference between them. Figure 5 is a simplified schematic. The PFD includes a programmable delay element that controls the width of the antibacklash pulse. This pulse ensures that no dead zone is in the PFD transfer function and minimizes phase noise and reference spurs. Two bits in the reference counter latch, ABP2 and ABP1, control the width of the pulse (see Table III).



Figure 5. PFD Simplified Schematic and Timing (In Lock)

MUXOUT AND LOCK DETECT

The output multiplexer on the ADF4001 family allows the user to access various internal points on the chip. The state of MUXOUT is controlled by M3, M2, and M1 in the function latch. Table V shows the full truth table. Figure 6 shows the MUXOUT section in block diagram form.





Lock Detect

MUXOUT can be programmed for two types of lock detect: digital lock detect and analog lock detect. Digital lock detect is active high. When LDP in the R counter latch is set to 0, digital lock detect is set high when the phase error on three consecutive phase detector cycles is less than 15 ns. With LDP set to 1, five consecutive cycles of less than 15 ns are required to set the lock detect. It will stay set high until a phase error of greater than 25 ns is detected on any subsequent PD cycle. The N-channel open-drain analog lock detect should be operated with an external pull-up resistor of 10 k Ω nominal. When lock has been detected, this output will be high with narrow low-going pulses.

INPUT SHIFT REGISTER

The ADF4001 digital section includes a 24-bit input shift register, a 14-bit R counter, and a 13-bit N counter. Data is clocked into the 24-bit shift register on each rising edge of CLK. The data is clocked in MSB first. Data is transferred from the shift register to one of four latches on the rising edge of LE. The destination latch is determined by the state of the two control bits (C2, C1) in the shift register. These are the two LSBs, DB1 and DB0, as shown in the timing diagram of Figure 1. The truth table for these bits is shown in Table I. Table II shows a summary of how the latches are programmed.

Table I. C2, C1 Truth Table

Cont	trol Bits	
C2	C1	Data Latch
0	0	R Counter
0	1	N Counter
1	0	Function Latch
1	1	Initialization Latch

Table II. ADF4001 Family Latch Summary

	RESERV	ED	LOCK DETECT PRECISION	TE MC B	est DDE Its	AN BACK WII	ITI- LASH DTH	14-BIT REFERENCE COUNTER									CON BI	TROL TS					
DB23	DB22	DB21	DB20	DB19	DB18	DB17	DB16	DB15	DB14	DB13	DB12	DB11	DB10	DB9	DB8	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
x	x	x	LDP	T2	T1	ABP2	ABP1	R14	R13	R12	R11	R10	R9	R8	R7	R6	R5	R4	R3	R2	R1	C2 (0)	C1 (0)

N COUNTER LATCH

RESE	RVED	CP GAIN	13-BIT N COUNTER RESERVED														CONTROL BITS						
DB23	DB22	DB21	DB20	DB19	DB18	DB17	DB16	DB15	DB14	DB13	DB12	DB11	DB10	DB9	DB8	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
x	x	G1	N13	N12	N11	N10	N9	N8	N7	N6	N5	N4	N3	N2	N1	х	x	х	x	х	х	C2 (0)	C1 (1)

FUNCTION LATCH FASTLOCK MODE PHASE DETECTOR POLARITY FASTLOCK ENABLE COUNTER POWER-DOWN 1 CURRENT CURRENT TIMER COUNTER CP THREE-STATE POWER DOWN 2 михоит CONTROL RESERVED SETTING SETTING CONTROL CONTROL BITS 2 DB23 DB22 DB21 DB20 DB19 DB18 DB17 DB16 DB15 DB14 DB13 DB12 DB11 DB10 DB9 DB8 DB7 DB6 DB5 DB4 DB3 DB2 DB1 DB0 PD2 CPI6 CPI5 CPI4 CPI3 CPI2 CPI1 TC4 TC3 F5 F4 F2 M3 M2 M1 PD1 F1 C2 (1) C1 (0) х х TC2 TC1 F3

INITIALIZATION LATCH

RESERVED		POWER- DOWN 2	CURRENT SETTING 2			CURRENT SETTING 1			TIMER COUNTER CONTROL				FASTLOCK MODE	FASTLOCK ENABLE	CP THREE- STATE	PHASE DETECTOR POLARITY	(MUXO	UT OL	POWER- DOWN 1	COUNTER RESET	CON BI	TROL TS
DB23	DB22	DB21	DB20	DB19	DB18	DB17	DB16	DB15	DB14	DB13	DB12	DB11	DB10	DB9	DB8	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
x	x	PD2	CPI6	CPI5	CPI4	CPI3	CPI2	CPI1	TC4	тсз	TC2	TC1	F5	F4	F3	F2	МЗ	M2	M1	PD1	F1	C2 (1)	C1 (1)

X = DON'T CARE

RESERVED									14-BIT REFERENCE COUNTER												CONTROL BITS		
DB23	DB22	DB21	DB20	DB19	DB18	DB17	DB16	DB15	DB14	DB13	DB12	DB11	DB10	DB9	DB8	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
х	x	x	LDP	T2	T1	ABP2	ABP1	R14	R13	R12	R11	R10	R9	R8	R7	R6	R5	R4	R3	R2	R1	C2 (0)	C1 (0)
X = D0		RE		1	İ	1		1	1		1		1					1	I		1		
									_					V									_
										R14	R13	3	R12			R3	R	2	R1		DIVID	E RATI	<u> </u>
										0	0		0			0	0		1		1		
										0	0		0			0	1		1		2		
										0	0		0			1	0		0		4		
										:	:		:			:	:		:		:		
										÷	÷										16380		
																			, i		10000		
										1	1		1			1	0		1		16381		
										1	1		1			1	1		0		16382		
										1	1		1			1	1		1		16383		
						,																	
						ABP2	ABI	71	ANTIB	ACKLAS	H PULSE	E WIDTH											
						0	0		2.9ns														
						0	1		1.3ns														
						1 1	0		6.0ns 2.9ns														
				<u> </u>	•			-															
				TES	T MODE	BITS SH	IOULD																
				BES	ET TO 00) FOR NO	ORMAL																
]															
		_										_											
LDP OPERATION																							
		0		THREE CONSECUTIVE CYCLES OF PHASE DELAY LESS THAN																			
		1	15ns MUST OCCUR BEFORE LOCK DETECT IS SET. 1 FIVE CONSECUTIVE CYCLES OF PHASE DELAY LESS THAN																				
		ľ		15ns	MUST O	CCUR B	FORE	OCK D	ETECTI	S SET.													

Table III. Reference Counter Latch Map

Table IV.	N Counter	Latch Map
-----------	-----------	-----------

RESI	ERVED	CP GAIN					1	3-BIT N	COUNTE	R		RESE						ERVED)		CON BI	TROL TS	
DB23	DB22	DB21	DB20	DB19	DB18	DB17	DB16	DB15	DB14	DB13	DB12	DB11	DB10	DB9	DB8	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0
x	x	G1	N13	N12	N11	N10	N9	N8	N7	N6	N5	N4	N3	N2	N1	х	х	х	x	x	х	C2 (0)	C1 (1)
																X = D	ON'T C	ARE					
				N13	I	N12	N11			N3		N2	N1		N COU	JNTER	DIVIDE	RATIC					
				0 0 0		0 0 0	0 0 0			0 0 0		0 1 1	1 0 1		1 2 3								
				0		0	0			1		0	0		4								
							:			•					0100								
						1	1			1		0	1		8189								
				1		1	1			1		1	0		8190								
				1		1	1			1		1	1		8191								
		F4 (FUN	ICTION	LATCH)	V																		
		FASTLO	JCK EN	ABLE	CP G																		
		0			1	1	IS PERM HARGE	IANEN			NG												
		1			0	2 C	IS PERM	IANEN PUMP (LY USE	D IT SETT	NG												
	.	1			1	1 C	IS USEE) PUMP (IT IS													
				SWITCHED TO SETTING 2. THE TIME SPENT IN SETTING 2 IS DEPENDENT ON WHICH FASTLOCK MODE IS USED. SEE FUNCTION LATCH DESCRIPTION.																			
	↓└																						
THES BY 1	E BITS THE DE DON'T C	ARE N VICE A CARE B	OT USEI ND ARE ITS.																				

Table V. Function Latch Map

RESE	RVED	POWER- DOWN 2	, c	CURREN SETTINC 2	T	C	URREN SETTING 1	T		TIMER C CON	OUNTEF	1	FASTLOCK MODE	FASTLOCK ENABLE	CP THREE- STATE	PHASE	POLARITY	MI CO	JXOL NTRO	JT OL	POWER- DOWN 1	COUNTER RESET	CONTR	DL
DB23	DB22	DB21	DB20	DB19	DB18	DB17	DB16	DB15	DB14	DB13	DB12	DB11	DB10	DB9	DB8	DB	7 D	DB6 С	B5	DB4	DB3	DB2	DB1 D	во
х	x	PD2	CPI6	CPI5	CPI4	CPI3	CPI2	CPI1	TC4	тСз	TC2	TC1	F5	F4	F3	F2	N	МЗ	M2	M1	PD1	F1	C2 (1) C1	(0)
DB23 X X = DO	DB22 X N'T CAR	DB21 PD2 E	DB20 CPI6	DB19 CPI5	DB18 CPI4 TC4 0 0 0 0 0 0 0 0 0 1 1	DB17 CPI3	DB16 CPI2 TC3 0 0 0 0 1 1 1 1 0 0 0	DB15 CPI1 TC 0 1 1 1 0 0 1 1 1 0 0 1	DB14 TC4	DB13 TC3 TC1 0 1 0 1 0 1 0 1 0 1 0 1 0 1 0	DB12 TC2 TC2 TI (P 3 7 11 15 19 23 27 31 35 39 43	F4 0 1 1 SPCYC	DB10 F5	DB9 F4 F3 0 1 V S5 5 5 5 5 7 7 7 7 7 7 7 7 7 7 7 7 7 7	DB8 F3 F3 CH NC TH FAST FAST FAST FAST FAST	DB F2 0 1 HARGI DRMA IREE-3 LOCK LOCK LOCK LOCK LOCK 1 1 0 1 1 1 1	PHAS POLA POSI E PUN L STAT DISA MOD	DB6 C M3 - M3 - M3 - M3 - M3 - M3 - M4 - M4 - M4 - M5 - M6 - M7 - M8 - M1 - 0 1 0 1 0 1		DB4 M1 TOR T T T T T T HTRE DIGIT/ N OUTP! THRE DIGIT/ N OUTP! THRE SERIA DGND	DB3 PD1 UT 	F1 F1 0 1 E OUTIT K DETI JTPUT JTPUT T DPEN-I A OUTF	COUNTE OPERAT NORMA R, N CO HELD IN	R (0) JNTER RESET
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					1		1 1	1		0	59	,) ;												
			_																					
				CPI6 CPI3	CPI	5	CP14 CPI1	2.7	'kΩ	I _{CP} (m.	A)	kΩ												
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RESE	RVED	POWER- DOWN 2	C	URREN ETTINO 2	IT G	C	URREN SETTING 1	T		TIMER C CONT	OUNTEF	3	FASTLOCK MODE	FASTLOCK ENABLE	CP THREE-	STATE PHASE DFTECTOR	POLARITY	ML CO	JXOU NTRO	IT DL	POWER- DOWN 1	COUNTER RESET	CON Bi	TROL TS	
DB23	DB22	DB21	DB20	DB19	DB18	DB17	DB16	DB15	DB14	DB13	DB12	DB11	DB10	DB9	DB	8 DE	37	DB6 D	B5	DB4	DB3	DB2	DB1	DB0	
х	x	PD2	CPI6	CPI5	CPI4	CPI3	CPI2	CPI1	TC4	тсз	TC2	TC1	F5	F4	F3	E	2	M3	M2	M1	PD1	F1	C2 (1)	C1 (1)	
X = DOI	L I	•										F4 0 1 1	F X 0 1	F3 0 1	FA: FA: FA:	F2 0 1 CHARC NORM/ THREE STLOCI STLOCI STLOCI	PHA POL NEC POS GE PL AL S-STA K MO K MO K MO	ASE DE LARITY GATIVE SITIVE JMP OU TE DE ABLED DE 1 DE 2	TPU'	T		F 1 0 1	COUN OPER NORM R, N (HELD	ITER ATIOI IAL :OUN' IN RE	I IER ISET
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				CPI6 CPI3	1 1 1 1 CPI: CPI: 0	5	1 1 1 CP14 CP11 0	0 0 1 1 2.7 1.0	7kΩ 088	0 1 0 1 I _{CP} (m. 4.7kΩ 0.625	A)	i kΩ 294													
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Table VI. Initialization Latch Map

FUNCTION LATCH

With C2, C1 set to 1, 0, the on-chip function latch will be programmed. Table V shows the input data format for programming the function latch.

Counter Reset

DB2 (F1) is the counter reset bit. When this is 1, the R counter and the A, B counters are reset. For normal operation, this bit should be 0. Upon powering up, the F1 bit needs to be disabled, and the N counter resumes counting in close alignment with the R counter. (The maximum error is one prescaler cycle.)

Power-Down

DB3 (PD1) and DB21 (PD2) on the ADF4001 family provide programmable power-down modes. They are enabled by the CE pin.

When the CE pin is low, the device is immediately disabled regardless of the states of PD2, PD1.

In the programmed asynchronous power-down, the device powers down immediately after latching a 1 into Bit PD1, with the condition that PD2 has been loaded with a 0.

In the programmed synchronous power-down, the device powerdown is gated by the charge pump to prevent unwanted frequency jumps. Once the power-down is enabled by writing a 1 into Bit PD1 (on condition that a 1 has also been loaded to PD2), the device will go into power-down on the occurrence of the next charge pump event.

When a power-down is activated (either synchronous or asynchronous mode, including CE pin activated power-down), the following events occur:

- All active dc current paths are removed.
- The R, N, and timeout counters are forced to their load state conditions.
- The charge pump is forced into three-state mode.
- The digital clock detect circuitry is reset.
- The RF_{IN} input is debiased.
- The reference input buffer circuitry is disabled.
- The input register remains active and capable of loading and latching data.

MUXOUT Control

The on-chip multiplexer is controlled by M3, M2, M1 on the ADF4001. Table V shows the truth table.

Fastlock Enable Bit

DB9 of the function latch is the fastlock enable bit. Only when this is 1 is fastlock enabled.

Fastlock Mode Bit

DB10 of the function latch is the fastlock mode bit. When fastlock is enabled, this bit determines which fastlock mode is used. If the fastlock mode bit is 0, fastlock mode 1 is selected; if the fastlock mode bit is 1, fastlock mode 2 is selected.

Fastlock Mode 1

The charge pump current is switched to the contents of Current Setting 2.

The device enters fastlock by having a 1 written to the CP gain bit in the N counter latch. The device exits fastlock by having a 0 written to the CP gain bit in the AB counter latch.

Fastlock Mode 2

The charge pump current is switched to the contents of Current Setting 2.

The device enters fastlock by having a 1 written to the CP gain bit in the N counter latch. The device exits fastlock under the control of the timer counter. After the timeout period determined by the value in TC4–TC1, the CP gain bit in the N counter latch is automatically reset to 0 and the device reverts to normal mode instead of fastlock. See Table V for the timeout periods.

Timer Counter Control

The user has the option of programming two charge pump currents. The intent is that the Current Setting 1 is used when the RF output is stable and the system is in a static state. Current Setting 2 is meant to be used when the system is dynamic and in a state of change (i.e., when a new output frequency is programmed). The normal sequence of events is as follows.

The user initially decides what the preferred charge pump currents are going to be. For example, they may choose 2.5 mA as Current Setting 1 and 5 mA as Current Setting 2.

At the same time, they must also decide how long they want the secondary current to stay active before reverting to the primary current. This is controlled by the Timer Counter Control Bits DB14 to DB11 (TC4–TC1) in the function latch. The truth table is given in Table V.

Now, when the user wishes to program a new output frequency, they can simply program the N counter latch with new value for N. At the same time, they can set the CP gain bit to a 1, which sets the charge pump with the value in CPI6–CPI4 for a period of time determined by TC4–TC1. When this time is up, the charge pump current reverts to the value set by CPI3–CPI1. At the same time, the CP gain bit in the N counter latch is reset to 0 and is now ready for the next time that the user wishes to change the frequency.

Note that there is an enable feature on the timer counter. It is enabled when Fastlock Mode 2 is chosen by setting the fastlock mode bit (DB10) in the function latch to 1.

Charge Pump Currents

CPI3, CPI2, CPI1 program Current Setting 1 for the charge pump. CPI6, CPI5, CPI4 program Current Setting 2 for the charge pump. The truth table is given in Table V.

PD Polarity

This bit sets the PD polarity bit (see Table V).

CP Three-State

This bit sets the CP output pin. With the bit set high, the CP output is put into three-state. With the bit set low, the CP output is enabled.

INITIALIZATION LATCH

When C2, C1 = 1, 1, the initialization latch is programmed. This is essentially the same as the function latch (programmed when C2, C1 = 1, 0).

However, when the initialization latch is programmed, there is an additional internal reset pulse applied to the R and N counters. This pulse ensures that the N counter is at a load point when the N counter data is latched, and the device will begin counting in close phase alignment.

If the latch is programmed for synchronous power-down (the CE pin is high; PD1 bit is high; and PD2 bit is low), the internal pulse also triggers this power-down. The oscillator input buffer is unaffected by the internal reset pulse, so close phase alignment is maintained when counting resumes.

When the first N counter data is latched after initialization, the internal reset pulse is again activated. However, successive N counter loads will not trigger the internal reset pulse.

DEVICE PROGRAMMING AFTER INITIAL POWER-UP

After initially powering up the device, there are three ways to program the device.

Initialization Latch Method

Apply V_{DD}.

Program the initialization latch (11 in 2 LSB of input word). Make sure that F1 bit is programmed to 0.

Do an R load (00 in 2 LSBs).

Do an N load (01 in 2 LSBs).

When the initialization latch is loaded, the following occurs:

- 1. The function latch contents are loaded.
- 2. An internal pulse resets the R, N, and timeout counters to load state conditions and also three-states the charge pump. Note that the prescaler band gap reference and the oscillator input buffer are unaffected by the internal reset pulse, allowing close phase alignment when counting resumes.
- 3. Latching the first N counter data after the initialization word will activate the same internal reset pulse. Successive N loads will not trigger the internal reset pulse unless there is another initialization.

CE Pin Method

Apply V_{DD}.

Bring CE low to put the device into power-down. This is an asynchronous power-down in that it happens immediately.

Program the function latch (10). Program the R counter latch (00). Program the N counter latch (01).

Bring CE high to take the device out of power-down. The R and AB counters will now resume counting in close alignment.

Note that after CE goes high, a duration of 1 μ s may be required for the prescaler band gap voltage and oscillator input buffer bias to reach steady state.

CE can be used to power the device up and down to check for channel activity. The input register does not need to be reprogrammed each time the device is disabled and enabled as long as it has been programmed at least once after $V_{\rm DD}$ was initially applied.

Counter Reset Method

Apply V_{DD}.

Do a function latch load (10 in 2 LSBs). As part of this, load 1 to the F1 bit. This enables the counter reset.

Do an R counter load (00 in 2 LSBs).

Do an N counter load (01 in 2 LSBs).

Do a function latch load (10 in 2 LSBs). As part of this, load 0 to the F1 bit. This disables the counter reset.

This sequence provides the same close alignment as the initialization method. It offers direct control over the internal reset. Note that counter reset holds the counters at load point and three-states the charge pump but does not trigger synchronous power-down. The counter reset method requires an extra function latch load compared to the initialization latch method.

APPLICATION

Extremely Stable, Low Jitter Reference Clock for GSM Base Station Transmitter

Figure 7 shows the ADF4001 being used with a VCXO to produce an extremely stable, low jitter reference clock for a GSM base station local oscillator (LO).



Figure 7. Low Jitter, Stable Clock Source for GSM Base Station Local Oscillator Circuit

The system reference signal is applied to the circuit at REF_{IN} . Typical GSM systems would have a very stable OCXO as the clock source for the entire base station. However, distribution of this signal around the base station makes it susceptible to noise and spurious pickup. It is also open to pulling from the various loads it may need to drive.

The charge pump output of the ADF4001 (Pin 2 of the TSSOP) drives the loop filter and the 13 MHz VCXO. The VCXO output is fed back to the RF input of the ADF4001 and also drives the reference (REF_{IN}) for the LO. A T-circuit configuration provides 50 Ω matching between the VCXO output, the LO REF_{IN}, and the RF_{IN} terminal of the ADF4001.

COHERENT CLOCK GENERATION

When testing A/D converters, it is often advantageous to use a coherent test system, that is, a system that ensures a specific relationship between the A/D converter input signal and the A/D converter sample rate. Thus, when doing an FFT on this data, there is no longer any need to apply the window weighting function. Figure 8 shows how the ADF4001 can be used to handle all the possible combinations of the input signal frequency and sampling rate. The first ADF4001 is phase locked to a VCO. The output of the VCO is also fed into the N divider of the second ADF4001. This results in both ADF4001s being coherent with the REF_{IN}. Since the REF_{IN} comes from the signal generator, the MUXOUT signal of the second ADF4001 is coherent with the f_{IN} frequency to the ADC. This is used as f_S , the sampling clock.



Figure 8. Coherent Clock Generator

TRI-BAND CLOCK GENERATION CIRCUIT

In multiband applications, it is necessary to realize different clocks from one master clock frequency. For example, GSM uses a 13 MHz system clock, WCDMA uses 19.44 MHz, and CDMA uses 19.2 MHz. The circuit in Figure 9 shows how to use the ADF4001 to generate GSM, WCDMA, and CDMA system clocks from a single 52 MHz master clock. The low RF $f_{\rm MIN}$ specification and the ability to program R and N values as low as \div 1 makes the ADF4001 suitable for this. Other $f_{\rm OUT}$ clock frequencies can be realized using the formula

$$f_{OUT} = REF_{IN} \times (N \div R)$$

SHUTDOWN CIRCUIT

The circuit in Figure 10 shows how to shut down both the ADF4001 and the accompanying VCO. The ADG702 switch goes open circuit when a Logic 1 is applied to the IN input. The low cost switch is available in both SOT-23 and micro SOIC packages.



Figure 9. Tri-Band System Clock Generation



Figure 10. Local Oscillator Shutdown Circuit

INTERFACING

The ADF4001 family has a simple SPI[®] compatible serial interface for writing to the device. SCLK, SDATA, and LE control the data transfer. When LE (latch enable) goes high, the 24 bits that have been clocked into the input register on each rising edge of SCLK will be transferred to the appropriate latch. See Figure 1 for the Timing Diagram and Table I for the Latch Truth Table.

The maximum allowable serial clock rate is 20 MHz. This means that the maximum update rate possible for the device is 833 kHz or one update every 1.2 ms. This is certainly more than adequate for systems with typical lock times in hundreds of microseconds.

ADuC812 Interface

Figure 11 shows the interface between the ADF4001 family and the ADuC812 MicroConverter[®]. Since the ADuC812 is based on an 8051 core, this interface can be used with any 8051-based microcontroller. The MicroConverter is set up for SPI master mode with CPHA = 0. To initiate the operation, the I/O port driving LE is brought low. Each latch of the ADF4001 family needs a 24-bit word. This is accomplished by writing three 8-bit bytes from the MicroConverter to the device. When the third byte has been written, the LE input should be brought high to complete the transfer.

On first applying power to the ADF4001 family, it needs three writes (one each to the R counter latch, the N counter latch, and the initialization latch) for the output to become active.

I/O port lines on the ADuC812 are also used to control powerdown (CE input) and to detect lock (MUXOUT configured as lock detect and polled by the port input).

When operating in the mode described, the maximum SCLOCK rate of the ADuC812 is 4 MHz. This means that the maximum rate at which the output frequency can be changed will be 166 kHz.



Figure 11. ADuC812 to ADF4001 Family Interface

ADSP-2181 Interface

Figure 12 shows the interface between the ADF4001 family and the ADSP-21xx digital signal processor. The ADF4001 family needs a 24-bit serial word for each latch write. The easiest way to accomplish this using the ADSP-21xx family is to use the autobuffered transmit mode of operation with alternate framing. This provides a means for transmitting an entire block of serial data before an interrupt is generated. Set up the word length for 8 bits and use three memory locations for each 24-bit word. To program each 24-bit latch, store the three 8-bit bytes, enable the autobuffered mode, and then write to the transmit register of the DSP. This last operation initiates the autobuffer transfer.



Figure 12. ADSP-21xx to ADF4001 Family Interface

PCB DESIGN GUIDELINES FOR CHIP SCALE PACKAGE

The leads on the chip package (CP-20) are rectangular. The printed circuit board pad for these should be 0.1 mm longer than the package lead length and 0.05 mm wider than the package lead width. The lead should be centered on the pad to ensure that the solder joint size is maximized.

The bottom of the chip scale package has a central thermal pad. The thermal pad on the printed circuit board should be at least as large as this exposed pad. On the printed circuit board, there should be a clearance of at least 0.25 mm between the thermal pad and the inner edge of the pad pattern. This will ensure that shorting is avoided.

Thermal vias may be used on the printed circuit board thermal pad to improve thermal performance of the package. If vias are used, they should be incorporated in the thermal pad at 1.2 mm pitch grid. The via diameter should be between 0.3 mm and 0.33 mm, and the via barrel should be plated with 1 oz. copper to plug the via.

The user should connect the printed circuit board thermal pad to AGND.

OUTLINE DIMENSIONS



COMPLIANT TO JEDEC STANDARDS MO-220-WGGD-1.

Figure 14. 20-Lead Lead Frame Chip Scale Package [LFCSP_WQ] 4 mm × 4 mm, Very Very Thin Quad (CP-20-6) Dimensions shown in millimeters 08-16-2010-B

ORDERING GUIDE

Model ¹	Temperature Range	Package Description	Package Option
ADF4001BRU	-40°C to +85°C	16-Lead Thin Shrink Small Outline Package [TSSOP]	RU-16
ADF4001BRU-REEL	–40°C to +85°C	16-Lead Thin Shrink Small Outline Package [TSSOP]	RU-16
ADF4001BRU-REEL7	–40°C to +85°C	16-Lead Thin Shrink Small Outline Package [TSSOP]	RU-16
ADF4001BRUZ	–40°C to +85°C	16-Lead Thin Shrink Small Outline Package [TSSOP]	RU-16
ADF4001BRUZ-R7	–40°C to +85°C	16-Lead Thin Shrink Small Outline Package [TSSOP]	RU-16
ADF4001BRUZ-RL	–40°C to +85°C	16-Lead Thin Shrink Small Outline Package [TSSOP]	RU-16
ADF4001BCPZ	–40°C to +85°C	20-Lead Lead Frame Chip Scale Package [LFCSP_WQ]	CP-20-6
ADF4001BCPZ-RL	–40°C to +85°C	20-Lead Lead Frame Chip Scale Package [LFCSP_WQ]	CP-20-6
ADF4001BCPZ-RL7	–40°C to +85°C	20-Lead Lead Frame Chip Scale Package [LFCSP_WQ]	CP-20-6
EV-ADF4001SD1Z		Evaluation Board	

 1 Z = RoHS Compliant Part.

REVISION HISTORY

	4/13-	Rev.	A	to	Rev.	B
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Changed RF_{IN}A to RF_{IN}B from $\pm 320 \text{ mV}$ to $\pm 600 \text{ mV}$	3
Updated Outline Dimensions	16
Changes to Ordering Guide	16
10/03—Rev. 0 to Rev. A	
Changes to Specifications	2
Edits to Ordering Guide	3
Changes to Pin Configurations	4
Updated Outline Dimensions	16

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