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General Description

The MAX1421 is a 3.3V. 12-bit analog-to-digital converter (ADC), featuring a fully-differential input, pipelined, 12-stage ADC architecture with wideband track-and-hold (T/H) and digital error correction incorporating a fully-differential signal path. The MAX1421 is optimized for low-power, high-dynamic performance applications in imaging and digital communications. The converter operates from a single 3.3V supply, consuming only 188mW while delivering a typical signal-tonoise ratio (SNR) of 66dB at an input frequency of 15MHz and a sampling frequency of 40Msps. The fullydifferential input stage has a small signal -3dB bandwidth of 400MHz and may be operated with single-ended inputs.

An internal 2.048V precision bandgap reference sets the full-scale range of the ADC. A flexible reference structure accommodates an internal or externally applied buffered or unbuffered reference for applications requiring increased accuracy or a different input voltage range.

In addition to low operating power, the MAX1421 features two power-down modes, a reference power-down and a shutdown mode. In reference power-down, the internal bandgap reference is deactivated, resulting in a typical 2mA supply current reduction. For idle periods, a full shutdown mode is available to maximize power savings.

The MAX1421 provides parallel, offset binary, CMOScompatible three-state outputs.

The MAX1421 is available in a 7mm x 7mm, 48-pin TQFP package, and is specified over the commercial (0°C to +70°C) and the extended industrial (-40°C to +85°C) temperature ranges.

Pin-compatible higher- and lower-speed versions of the MAX1421 are also available. Please refer to the MAX1420 data sheet for a frequency of 60Msps and the MAX1422 data sheet for a frequency of 20Msps.

Applications

Medical Ultrasound Imaging CCD Pixel Processing Data Acquisition Radar IF and Baseband Digitization

Functional Diagram appears at end of data sheet.

Features

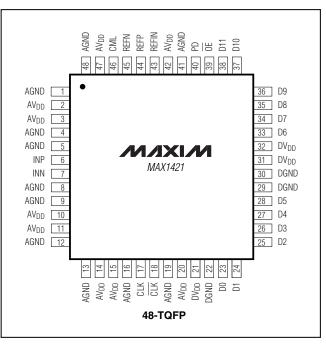
- ♦ Single 3.3V Power Supply
- ♦ 67dB SNR at f_{IN} = 5MHz
- ♦ 66dB SNR at f_{IN} = 15MHz
- ♦ Internal, 2.048V Precision Bandgap Reference
- ♦ Differential, Wideband Input T/H Amplifier
- ♦ Power-Down Modes 180mW (Reference Shutdown Mode) 10µW (Shutdown Mode)
- ♦ Space-Saving 48-Pin TQFP Package

Ordering Information

PART*	TEMP RANGE	PIN- PACKAGE	PKG CODE
MAX1421CCM	0°C to +70°C	48 TQFP	C48-2
MAX1421ECM	-40°C to +85°C	48 TQFP	C48-2
MAX1421ECM+	-40°C to +85°C	48 TQFP	C48-2

⁺Denotes lead-free package.

Pin Configuration



MIXIM

Maxim Integrated Products 1

ABSOLUTE MAXIMUM RATINGS

AV _{DD} , DV _{DD} to AGND0.3V to +4V	
DV _{DD} , AV _{DD} to DGND0.3V to +4V	
DGND to AGND0.3V to +0.3V	
INP, INN, REFP, REFN, REFIN,	
CML, CLK, CLK,(AGND - 0.3V) to (AV _{DD} + 0.3V)	
D0-D11, OE, PD(DGND - 0.3V) to (DV _{DD} + 0.3V)	
Continuous Power Dissipation ($T_A = +70^{\circ}C$)	
48-Pin TOFP (derate 12 5mW/°C above +70°C) 1000mW	

Maximum Junction Temperature	+150°C
Operating Temperature Ranges	
MAX1421CCM	0°C to +70°C
MAX1421ECM	40°C to +85°C
Storage Temperature Range	65°C to +150°C
Lead Temperature (soldering, 10s)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

 $(V_{AVDD} = V_{DVDD} = 3.3V, AGND = DGND = 0, V_{IN} = \pm 1.024V,$ differential input voltage at -0.5dB FS, internal reference, f_{CLK} = 40MHz (50% duty cycle), digital output load C_L \approx 10pF, T_A \geq +25°C guaranteed by production test, T_A < +25°C guaranteed by design and characterization. Typical values are at T_A = +25°C.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
DC ACCURACY	•						
Resolution	RES			12		Bits	
Differential Newlineauity	DNII	T _A = +25°C, no missing codes	-1		+1	LSB	
Differential Nonlinearity	DNL	TA = TMIN to TMAX		±0.5		LSB	
Integral Nonlinearity	INL	$T_A = T_{MIN}$ to T_{MAX}		±2		LSB	
Midscale Offset	MSO		-3	±.75	+3	%FSR	
Midscale Offset Temperature Coefficient	MSOTC			3 × 10 ⁻⁴		%/°C	
		Internal reference (Note 1)	-5	+0.1	+5		
Coin France	٥٦	External reference applied to REFIN (Note 2)	-5	±3	+5	%FSR	
Gain Error	GE	External reference applied to REFP, CML, and REFN (Note 3)	-1.5	±0.5	+1.5	%F5K	
Gain-Error Temperature Coefficient	GETC	External reference applied to REFP, CML, and REFN (Note 3)		15 × 10 ⁻⁶		%/°C	
DYNAMIC PERFORMANCE (fclk	= 40MHz, 4	1096-point FFT)				•	
Oissaulta Naisa Datia	CNID	f _{IN} = 5MHz		67		-ID	
Signal-to-Noise Ratio	SNR	f _{IN} = 15MHz, T _A = +25°C	62	66		dB	
Courious Free Dynamic Dange	SFDR	$f_{IN} = 5MHz$		73		dBc	
Spurious-Free Dynamic Range	SEDR	$f_{IN} = 15MHz$, $T_A = +25^{\circ}C$	64	70		UDC	
Total Harmonic Distortion	THD	$f_{IN} = 5MHz$		-74		dBc	
Total Harmonic Distortion	טחו	$f_{IN} = 15MHz$, $T_A = +25^{\circ}C$		-69	-62	UDC	
Signal-To-Noise Plus Distortion	SINAD	$f_{IN} = 5MHz$		66		dB	
Signal-10-140ise Filds Distortion	SINAD	$f_{IN} = 15MHz$, $T_A = +25^{\circ}C$	60	63.5		GD	
Effective Number of Bits	ENOB	$f_{IN} = 5MHz$		10.7		Bits	
Ellective Number of bits EN		$f_{IN} = 15MHz, T_A = +25^{\circ}C$	60	10.3		טונס	
Two-Tone Intermodulation Distortion	IMDTT	f _{IN1} = 11.569MHz, f _{IN2} = 13.445MHz (Note 4)		-80		dBc	

ELECTRICAL CHARACTERISTICS (continued)

 $(V_{AVDD} = V_{DVDD} = 3.3V, AGND = DGND = 0, V_{IN} = \pm 1.024V, differential input voltage at -0.5dB FS, internal reference, fCLK = 40MHz (50% duty cycle), digital output load CL <math>\approx$ 10pF, TA \geq +25°C guaranteed by production test, TA < +25°C guaranteed by design and characterization. Typical values are at TA = +25°C.)

PARAMETER	SYMBOL	CONDITIONS	MIN TYP MAX	UNITS
Differential Gain	DG		±1	%
Differential Phase	DP		±0.25	degrees
ANALOG INPUTS (INP, INN, CM	L)			
Input Resistance	R _{IN}	Either input to ground	32.5	kΩ
Input Capacitance	C _{IN}	Either input to ground	4	рF
Common-Mode Input Level (Note 5)	VCML		Vavdd × 0.5	V
Common-Mode Input Voltage Range (Note 5)	VCMVR		V _{CML} ±5%	V
Differential Input Range	V _{IN}	V _{INP} - V _{INN} (Note 6)	±V _{DIFF}	V
Small-Signal Bandwidth	BW _{-3dB}	(Note 7)	400	MHz
Large-Signal Bandwidth	FPBW-3dB	(Note 7)	150	MHz
Overvoltage Recovery	OVR	1.5 × FS input	1	Clock Cycle
INTERNAL REFERENCE (REFIN	bypassed w	vith 0.22µF in parallel with 1nF)		
Common-Mode Reference Input Voltage	VCML	At CML	VAVDD × 0.5	V
Positive Reference Voltage Range	V _{REFP}	At REFP	V _{CML} + 0.512	V
Negative Reference Voltage Range	VREFN	At REFN	V _{CML} - 0.512	V
Differential Reference Voltage Range	V _{DIFF}	(Note 6)	1.024 ±5%	V
Differential Reference Temperature Coefficient	REFTC		±100	ppm/°C
EXTERNAL REFERENCE (VREFIN	= 2.048V)			
REFIN Input Resistance	R _{IN}	(Note 8)	5	kΩ
REFIN Input Capacitance	C _{IN}		10	рF
REFIN Reference Input Voltage	V _{REFIN}		2.048 ±10%	V
Differential Reference Voltage	V _{DIFF}	(Note 6)	0.92 × VREFIN / 1.08 × VREFIN / 2 VREFIN / 2 2	V
EXTERNAL REFERENCE (VREFI	N = AGND, r	eference voltage applied to REFP, REFN, and	CML)	
REFP, REFN, CML Input Current	I _{IN}		-200 +200	μΑ
REFP, REFN, CML Input Capacitance	CIN		15	рF

ELECTRICAL CHARACTERISTICS (continued)

 $(V_{AVDD} = V_{DVDD} = 3.3V, AGND = DGND = 0, V_{IN} = \pm 1.024V,$ differential input voltage at -0.5dB FS, internal reference, f_{CLK} = 40MHz (50% duty cycle), digital output load C_L \approx 10pF, T_A \geq +25°C guaranteed by production test, T_A < +25°C guaranteed by design and characterization. Typical values are at T_A = +25°C.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Differential Reference Voltage Range	VDIFF	(Note 6)		1.024 ±10%		V
CML Input Voltage Range	VCML			1.65 ±10%		V
REFP Input Voltage Range	VREFP			V _{CML} + V _{DIFF} / 2		V
REFN Input Voltage Range	V _{REFN}			V _{CML} - V _{DIFF} / 2		V
DIGITAL INPUTS (CLK, CLK, OE	, PD)		•			
Input Logic-High	VIH		0.7 × V _{DVDD}			V
Input Logic-Low	VIL				0.3 × V _{DVDD}	V
		CLK, CLK		±330		
Input Current		PD	-20		+20	μΑ
		ŌĒ	-20		+20	
Input Capacitance				10		рF
DIGITAL OUTPUTS (D0-D11)	•					1
Output Logic-High	VoH	I _{OH} = 200μA	V _D VDD - 0.5		V_{DVDD}	V
Output Logic-Low	V _{OL}	I _{OL} = -200μA	0		0.5	V
Three-State Leakage			-10		+10	μΑ
Three-State Capacitance				2		pF
POWER REQUIREMENTS						
Analog Supply Voltage	V _{AVDD}		3.135	3.3	3.465	V
Digital Supply Voltage	V _{DVDD}		2.7	3.3	3.6	V
Analog Supply Current	lavdd			52	65	mA
Analog Supply Current with Internal Reference in Shutdown		REFIN = AGND		50	63	mA
Analog Shutdown Current		$PD = DV_{DD}$			20	μΑ
Digital Supply Current	IDVDD			5.5		mA
Digital Shutdown Current		$PD = DV_{DD}$			20	μΑ
Power Dissipation	PDISS	Analog power		188	214	mW
Power-Supply Rejection Ratio	PSRR	(Note 9)		±1		mV/V
TIMING CHARACTERISTICS						
Clock Frequency	fCLK	Figure 5	0.1		40.0	MHz
Clock High	tсн	Figure 5, clock period 25ns		12.5		ns
Clock Low	tcL	Figure 5, clock period 25ns		12.5		ns

ELECTRICAL CHARACTERISTICS (continued)

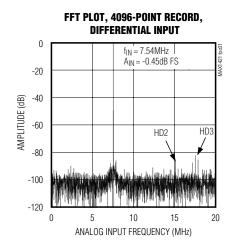
 $(V_{AVDD} = V_{DVDD} = 3.3V, AGND = DGND = 0, V_{IN} = \pm 1.024V, differential input voltage at -0.5dB FS, internal reference, f_{CLK} = 40MHz (50% duty cycle), digital output load C_L <math>\approx$ 10pF, T_A \geq +25°C guaranteed by production test, T_A < +25°C guaranteed by design and characterization. Typical values are at T_A = +25°C.)

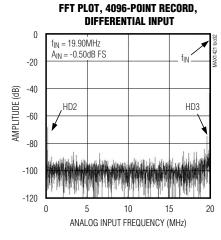
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Pipeline Delay (Latency)		Figure 5		7		f _{CLK} cycles
Aperture Delay	t _{AD}	Figure 9		2		ns
Aperture Jitter	tĄJ	Figure 9		2		ps
Data Output Delay	top	Figure 5	5	10	14	ns
Bus Enable Time	tBE	Figure 4		5		ns
Bus Disable Time	t _{BD}	Figure 4	_	5		ns

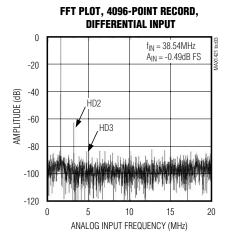
- Note 1: Internal reference, REFIN bypassed to AGND with a combination of 0.22µF in parallel with 1nF capacitor.
- Note 2: External 2.048V reference applied to REFIN.
- Note 3: Internal reference disabled. VREFIN = 0, VREFP = 2.162V, VCML = 1.65V, and VREFN = 1.138V.
- Note 4: IMD is measured with respect to either of the fundamental tones.
- Note 5: Specifies the common-mode range of the differential input signal supplied to the MAX1421.
- Note 6: VDIFF = VREFP VREFN.
- Note 7: Input bandwidth is measured at a 3dB level.
- Note 8: V_{REFIN} is internally biased to 2.048V through a $10k\Omega$ resistor.
- Note 9: Measured as the ratio of the change in mid-scale offset voltage for a ± 5% change in VAVDD using the internal reference.

Typical Operating Characteristics

 $(V_{AVDD} = V_{DVDD} = 3.3V, AGND = DGND = 0, V_{IN} = \pm 1.024V, differential input voltage, f_{CLK} = 40MHz (50% duty cycle), digital output load <math>C_L = 10pF, T_A = T_{MIN}$ to T_{MAX} unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$.)

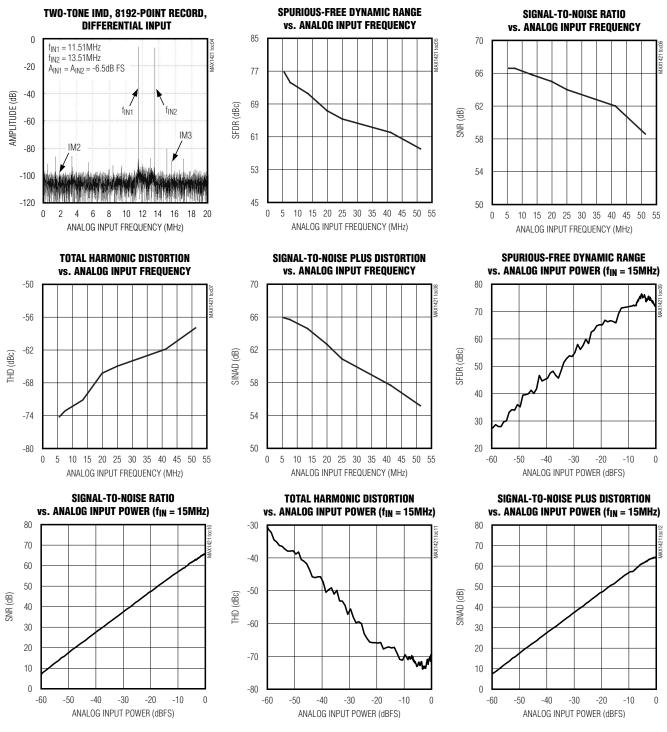






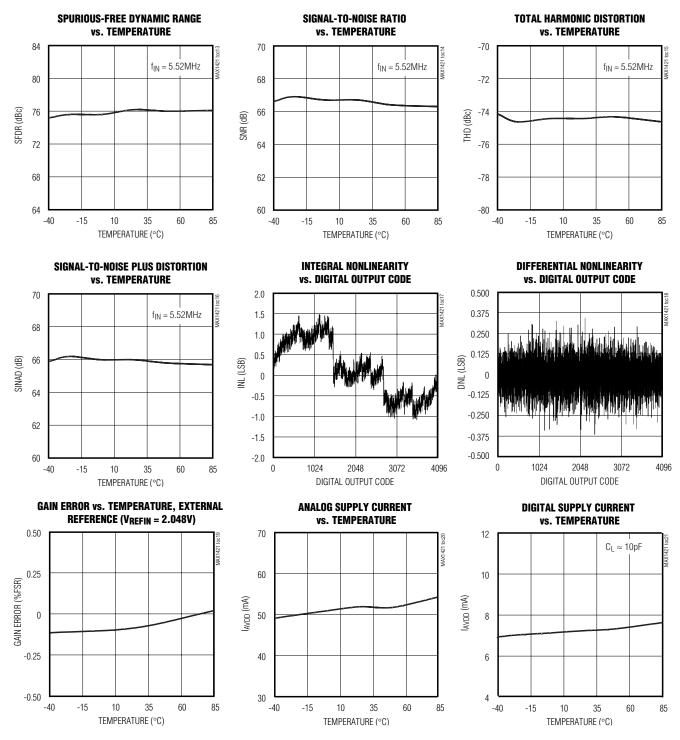
Typical Operating Characteristics (continued)

 $(V_{AVDD} = V_{DVDD} = 3.3V, AGND = DGND = 0, V_{IN} = \pm 1.024V, differential input voltage, f_{CLK} = 40MHz (50% duty cycle), digital output load <math>C_L = 10pF, T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$.)



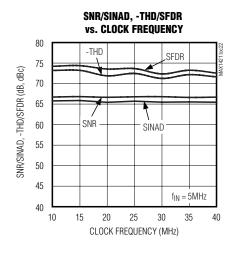
Typical Operating Characteristics (continued)

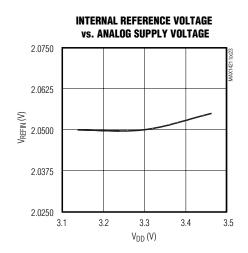
 $(V_{AVDD} = V_{DVDD} = 3.3V, AGND = DGND = 0, V_{IN} = \pm 1.024V, differential input voltage, f_{CLK} = 40MHz (50% duty cycle), digital output load <math>C_L = 10pF, T_A = T_{MIN}$ to T_{MAX} unless otherwise noted. Typical values are at $T_A = \pm 25^{\circ}C$.)

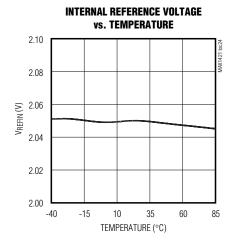


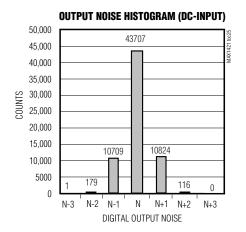
Typical Operating Characteristics (continued)

 $(V_{AVDD} = V_{DVDD} = 3.3V, AGND = DGND = 0, V_{IN} = \pm 1.024V, differential input voltage, f_{CLK} = 40MHz (50% duty cycle), digital output load <math>C_L = 10pF, T_A = T_{MIN}$ to T_{MAX} , unless otherwise noted. Typical values are at $T_A = +25^{\circ}C$.)









Pin Description

PIN	NAME	FUNCTION
1, 4, 5, 8, 9, 12, 13, 16, 19, 41, 48	AGND	Analog Ground. Connect all return paths for analog signals to AGND.
2, 3, 10, 11, 14, 15, 20, 42, 47	AV _{DD}	Analog Supply Voltage. For optimum performance bypass each pin to the closest AGND with a parallel combination of a 0.1µF and a 1nF capacitor. Connect a single 10µF and 1µF capacitor combination between AV _{DD} and AGND.
6	INP	Positive Analog Signal Input
7	INN	Negative Analog Signal Input
17	CLK	Clock Frequency Input. Clock frequency input ranges from 100kHz to 40MHz.
18	CLK	Complementary Clock Frequency Input. This input is used for differential clock inputs. If the ADC is driven with a single-ended clock, bypass CLK with a 0.1µF capacitor to AGND.
21, 31, 32,	DV _{DD}	Digital Supply Voltage. For optimum performance bypass each pin to the closest DGND with a parallel combination of a 0.1µF and a 1nF capacitor. Connect a single 10µF and 1µF capacitor combination between DV _{DD} and DGND.
22, 29, 30	DGND	Digital Ground
23–28	D0-D5	Digital Data Outputs. Data bits D0 through D5, where D0 represents the LSB.
33–38	D6-D11	Digital Data Outputs. D6 through D11, where D11 represents the MSB.
39	ŌĒ	Output Enable Input. A logic "1" on \overline{OE} places the outputs D0–D11 into a high-impedance state. A logic "0" allows for the data bits to be read from the outputs.
40	PD	Shutdown Input. A logic "1" on PD places the ADC into shutdown mode.
43	REFIN	External Reference Input. Bypass to AGND with a capacitor combination of 0.22µF in parallel with 1nF. REFIN can be biased externally to adjust reference levels and calibrate full-scale errors. To disable the internal reference, connect REFIN to AGND.
44	REFP	Positive Reference I/O. Bypass to AGND with a capacitor combination of $0.22\mu F$ in parallel with 1nF. With the internal reference disabled (REFIN = AGND), REFP should be biased to $V_{CML} + V_{DIFF} / 2$.
45	REFN	Negative Reference I/O. Bypass to AGND with a capacitor combination of $0.22\mu F$ in parallel with 1nF. With the internal reference disabled (REFIN = AGND), REFN should be biased to $V_{CML} - V_{DIFF} / 2$.
46	CML	Common-Mode Level Input. Bypass to AGND with a capacitor combination of 0.22µF in parallel with 1nF. With the internal reference disabled (REFIN = AGND).

Detailed Description

The MAX1421 uses a 12-stage, fully-differential, pipelined architecture (Figure 1) that allows for high-speed conversion while minimizing power consumption. Each sample moves through a pipeline stage every half-clock-cycle. Including the delay through the output latch, the latency is seven clock cycles.

A 2-bit (2-comparator) flash ADC converts the held-input voltage into a digital code. The following digital-to-analog converter (DAC) converts the digitized result back into an analog voltage, which is then subtracted from the original held-input signal. The resulting error signal is then multiplied by two, and the product is passed along to the next pipeline stage. This process is repeated until the signal has been processed by all 12 stages. Each stage provides a 1-bit resolution. Digital error correction compensates for ADC comparator offsets in each pipeline stage and ensures no missing codes.

Input Track-and-Hold Circuit

Figure 2 displays a simplified functional diagram of the input T/H circuit in both track-and-hold modes. In track mode, switches S1, S2a, S2b, S4a, S4b, S5a, and S5b are closed. The fully differential circuit passes the input signal to the two capacitors (C2a and C2b) through-switches (S4a and S4b). Switches S2a and S2b set the common mode for the transconductance amplifier

(OTA) input, and open simultaneously with S1, sampling the input waveform. The resulting differential voltage is held on capacitors C2a and C2b. Switches S4a and S4b are then opened before switches S3a and S3b, connecting capacitors C1a and C1b to the output of the amplifier, and switch S4c is closed. The OTA is used to charge capacitors C1a and C1b to the same values originally held on C2a and C2b. This value is then presented to the first-stage quantizer and isolates the pipeline from the fast-changing input. The wide-input bandwidth, T/H amplifier allows the MAX1421 to track and sample/hold analog inputs of high frequencies beyond Nyquist. The analog inputs INP and INN can be driven either differentially or single-ended. Match the impedance of INP and INN and set the common-mode voltage to midsupply (AVDD / 2) for optimum perfor-

Analog Input and Reference Configuration

The full-scale range of the MAX1421 is determined by the internally generated voltage difference between REFP (AVDD / 2 + VREFIN / 4) and REFN (AVDD / 2 - VREFIN / 4). The MAX1421's full-scale range is adjustable through REFIN, which provides a high input impedance for this purpose. REFP, CML (AVDD / 2), and REFN are internally buffered low impedance outputs.

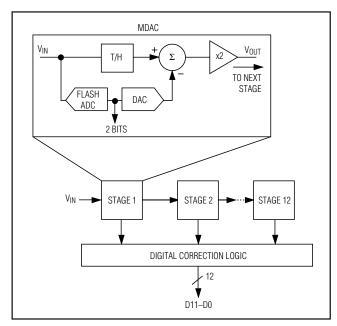


Figure 1. Pipelined Architecture

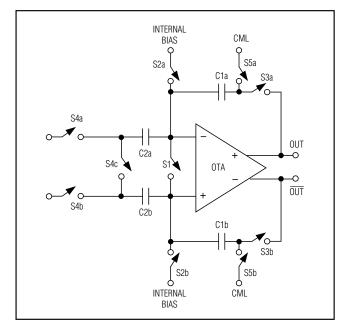


Figure 2. Internal Track-and-Hold Circuit

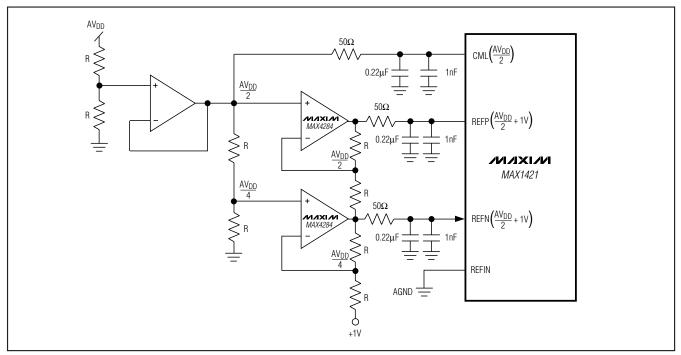


Figure 3. Unbuffered External Reference Drive—Internal Reference Disabled

The MAX1421 provides three modes of reference operation:

- Internal reference mode
- Buffered external reference mode
- Unbuffered external reference mode

In internal reference mode, the on-chip $\pm 2.048V$ bandgap reference is active and REFIN, REFP, CML, and REFN are left floating. For stability purposes, bypass REFIN, REFP, REFN, and CML with a capacitor network of $0.22\mu F$, in parallel with a 1nF capacitor to AGND.

In buffered external reference mode, the reference voltage levels can be adjusted externally by applying a stable and accurate voltage at REFIN.

In unbuffered external reference mode, REFIN is connected to AGND, which deactivates the on-chip buffers of REFP, CML, and REFN. With their buffers shut down, these nodes become high impedance and can be driven by external reference sources, as shown in Figure 3.

Clock Inputs (CLK, CLK)

The MAX1421's CLK and $\overline{\text{CLK}}$ inputs accept both single-ended and differential input operation, and accept CMOS-compatible clock signals. If CLK is driven with a

single-ended clock signal, bypass CLK with a 0.1µF capacitor to AGND. Since the interstage conversion of the device depends on the repeatability of the rising and falling edges of the external clock, use a clock with low jitter and fast rise and fall times (< 2ns). In particular, sampling occurs on the rising edge of the clock signal, requiring this edge to have the lowest possible jitter. Any significant aperture jitter limits the SNR performance of the ADC according to the following relationship:

$$SNR_{dB} = 20 \times log_{10} \left(\frac{1}{2\pi \times f_{IN} \times t_{AJ}} \right)$$

where $f_{\mbox{\footnotesize{IN}}}$ represents the analog input frequency and $t_{\mbox{\footnotesize{AJ}}}$ is the aperture jitter.

Clock jitter is especially critical for high input frequency applications. The clock input should always be considered as an analog input and routed away from any analog or digital signal lines.

The MAX1421 clock input operates with a voltage threshold set to AV_{DD} / 2. Clock inputs must meet the specifications for high and low periods, as stated in the *Electrical Characteristics*.

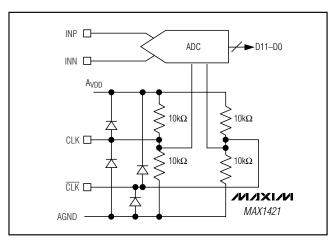


Figure 4. Simplified Clock Input Circuit

Figure 4 shows a simplified model of the clock input circuit. This circuit consists of two $10k\Omega$ resistors to bias the common-mode level of each input. This circuit may be used to AC-couple the system clock signal to the MAX1421 clock input.

Output Enable (\overline{OE}), Power-Down (PD), and Output Data (D0-D11)

With \overline{OE} high, the digital outputs enter a high-impedance state. If \overline{OE} is held low with PD high, the outputs are latched at the last value prior to the power-down. All data outputs, D0 (LSB) through D11 (MSB), are TTL/CMOS-logic compatible. There is a seven clock-

Table 1. MAX1421 Output Code for Differential Inputs

DIFFERENTIAL INPUT VOLTAGE*	DIFFERENTIAL INPUT	OFFSET BINARY
V _{REF} × 2047/2048	+FULL SCALE - 1LSB	1111 1111 1111
V _{REF} × 2046/2048	+FULL SCALE - 2LSB	1111 1111 1110
V _{REF} × 1/2048	+ 1 LSB	1000 0000 0001
0	Bipolar Zero	1000 0000 0000
-V _{REF} × 1/2048	- 1 LSB	0111 1111 1111
-V _{REF} × 2046/2048	-FULL SCALE + 1 LSB	0000 0000 0001
-V _{REF} × 2047/2048	-FULL SCALE	0000 0000 0000

^{*}VREF = VREFP - VREFN

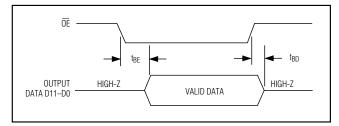


Figure 5. Output Enable Timing

cycle latency between any particular sample and its valid output data. The output coding is in offset binary format (Table 1).

The capacitive load on the digital outputs D0 through D11 should be kept as low as possible (\leq 10pF), to avoid large digital currents that could feed back into the analog portion of the MAX1421, thereby degrading its dynamic performance. The use of digital buffers (e.g., 74LVCH16244) on the digital outputs of the ADC can further isolate the digital outputs from heavy capacitive loads. To further improve the dynamic performance of the MAX1421, add small-series resistors of 100Ω to the digital output paths, close to the ADC. Figure 5 displays the timing relationship between output enable and data output.

System Timing Requirements

Figure 6 depicts the relationship between the clock input, analog input, and data output. The MAX1421 samples at the rising edge of CLK (falling edge of $\overline{\text{CLK}}$) and output data is valid seven clock cycles (latency) later. Figure 6 also displays the relationship between the input clock parameters and the valid output data.

_Applications Information

Figure 7 depicts a typical application circuit containing a single-ended to differential converter. The internal reference provides an AVDD / 2 output voltage for level-shifting purposes. The input is buffered and then split to a voltage follower and inverter. A lowpass filter at the input suppresses some of the wideband noise associated with high-speed op amps. Select the RISO and CIN values to optimize the filter performance and to suit a particular application. For the application in Figure 7, a RISO of 50Ω is placed before the capacitive load to prevent ringing and oscillation. The 22pF C_{IN} capacitor acts as a small bypassing capacitor.

Connecting C_{IN} from INN to INP may further improve dynamic performance.

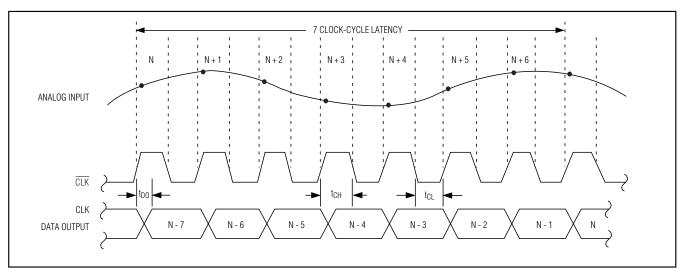


Figure 6. System and Output Timing Diagram

Using Transformer Coupling

An RF transformer (Figure 8) provides an excellent solution to convert a single-ended signal to a fully differential signal, required by the MAX1421 for optimum performance. Connecting the center tap of the transformer to CML provides an AVDD / 2 DC level shift to the input. Although a 1:1 transformer is shown, a 1:2 or 1:4 step-up transformer may be selected to reduce the drive requirements.

In general, the MAX1421 provides better SFDR and THD with fully differential input signals over single-ended input signals, especially for very high input frequencies. In differential input mode, even-order harmonics are suppressed and each of the inputs requires only half the signal swing compared to single-ended mode.

Single-Ended AC-Coupled Input Signal

Figure 9 shows an AC-coupled, single-ended application, using a MAX4108 op amp. This configuration provides high-speed, high-bandwidth, low noise, and low distortion to maintain the integrity of the input signal.

Grounding, Bypassing, and Board Layout

The MAX1421 requires high-speed board layout design techniques. Locate all bypass capacitors as close to the device as possible, preferably on the same side of the board as the ADC, using surface-mount devices for minimum inductance. Bypass REFP, REFN, REFIN, and CML with a parallel network of 0.22µF capacitors and 1nF to AGND. AVDD should be bypassed with a similar

network of a 10µF bipolar capacitor in parallel with two ceramic capacitors of 1nF and 0.1µF. Follow the same rules to bypass the digital supply DV_{DD} to DGND. Multilayer boards with separate ground and power planes produce the highest level of signal integrity. Consider the use of a split ground plane arrangement to match the physical location of the analog ground (AGND) and the digital output driver ground (DGND) on the ADCs package. The two ground planes should be joined at a single point so that the noisy digital ground currents do not interfere with the analog ground plane. Alternatively, all ground pins could share the same ground plane, if the ground plane is sufficiently isolated from any noisy, digital systems ground plane (e.g., downstream output buffer, DSP ground plane). Route high-speed digital signal traces away from sensitive analog traces and remove digital ground and power planes from underneath digital outputs. Keep all signal lines short and free of 90 degree turns.

Static Parameter Definitions

Integral Nonlinearity (INL)

Integral nonlinearity is the deviation of the values on an actual transfer function from a straight line. This straight-line can be either a best straight-line fit or a line drawn between the endpoints of the transfer function, once offset and gain errors have been nullified. The static linearity parameters for the MAX1421 are measured using the best straight-line fit method.

Differential Nonlinearity (DNL)

Differential nonlinearity is the difference between an actual step-width and the ideal value of 1LSB. A DNL

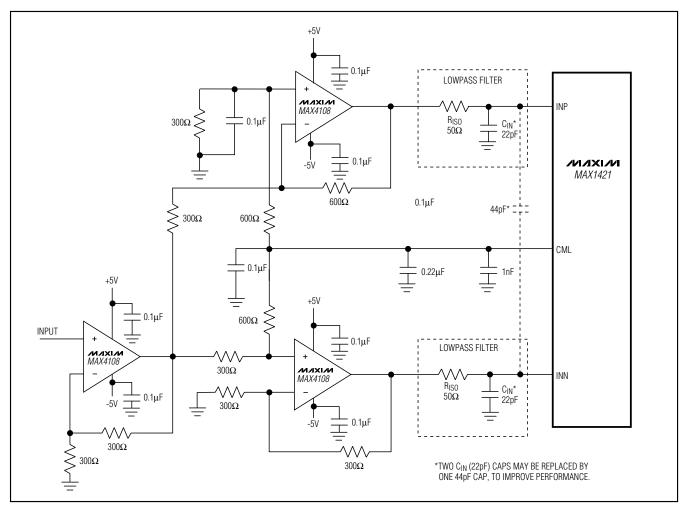


Figure 7. Typical Application Circuit for Single-Ended to Differential Conversion

error specification of less than 1LSB guarantees no missing codes.

Dynamic Parameter DefinitionsAperture Jitter

Figure 10 depicts the aperture jitter (t_{AJ}), which is the sample-to-sample variation in the aperture delay.

Aperture Delay

Aperture delay (t_{AD}) is the time defined between the falling edge of the sampling clock and the instant when an actual sample is taken (Figure 10).

Signal-to-Noise Ratio (SNR)

For a waveform perfectly reconstructed from digital samples, the theoretical maximum SNR is the ratio of

the full-scale analog input (RMS value) to the RMS quantization error (residual error). The ideal theoretical minimum analog-to-digital noise is caused by quantization error only and results directly from the ADCs resolution (N-bits):

$$SNR(MAX) = (6.02 \times N + 1.76)dB$$

In reality, there are other noise sources besides quantization noise e.g., thermal noise, reference noise, clock jitter, etc. SNR is computed by taking the ratio of the RMS signal to the RMS noise, which includes all spectral components minus the fundamental, the first four harmonics, and the DC offset.

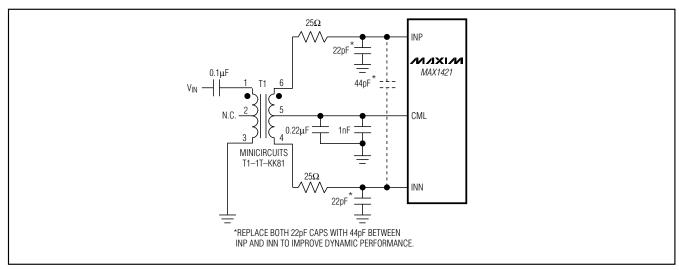


Figure 8. Using a Transformer for AC-Coupling

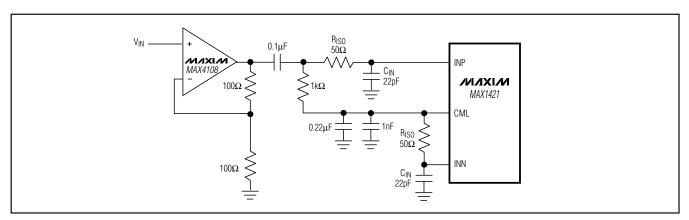


Figure 9. Single-Ended AC-Coupled Input Signal

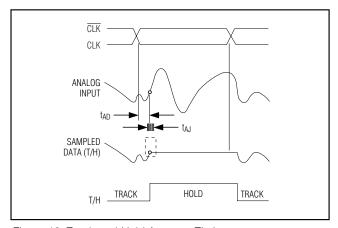


Figure 10. Track-and-Hold Aperture Timing

Signal-to-Noise Plus Distortion (SINAD)

SINAD is computed by taking the ratio of the RMS signal to all spectral components minus the fundamental and the DC offset.

Effective Number of Bits (ENOB)

ENOB specifies the dynamic performance of an ADC at a specific input frequency and sampling rate. An ideal ADC's error consists of quantization noise only. ENOB is computed from:

$$ENOB = \frac{SINAD-1.76}{6.02}$$

Total Harmonic Distortion (THD)

THD is typically the ratio of the RMS sum of the first four harmonics of the input signal to the fundamental itself. This is expressed as:

THD =
$$20 \times \log_{10} \left(\frac{\sqrt{(V_2^2 + V_3^2 + V_4^2 + V_5^2)}}{V_1} \right)$$

where V_1 is the fundamental amplitude, and V_2 through V_5 are the amplitudes of the 2nd- through 5th-order harmonics.

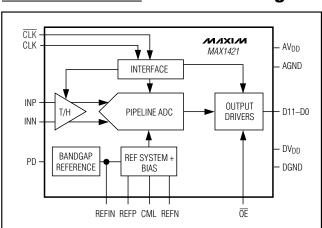
Spurious-Free Dynamic Range (SFDR)

SFDR is the ratio expressed in decibels of the RMS amplitude of the fundamental (maximum signal component) to the RMS value of the next largest spurious component, excluding DC offset.

Intermodulation Distortion (IMD)

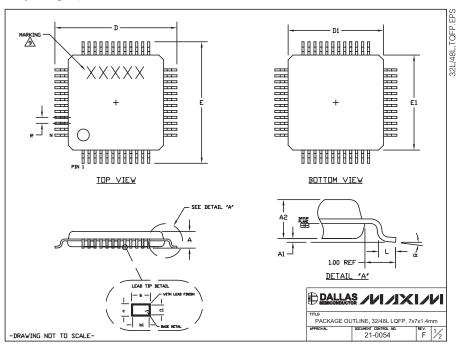
The two-tone IMD is the ratio expressed in decibels of either input tone to the worst 3rd-order (or higher) intermodulation products. The individual input tone levels are at -6.5dB full scale and their envelope is at -0.5dB full scale.

Functional Diagram



Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to www.maxim-ic.com/packages.)



NOTES:

- 1. ALL DIMENSIONING AND TOLERANCING CONFORM TO ANSI Y14.5-1982.
- 2. DATUM PLANE —H— IS LOCATED AT MOLD PARTING LINE AND COINCIDENT WITH LEAD, WHERE LEAD EXITS PLASTIC BODY AT BOTTOM OF PARTING LINE.
- DIMENSIONS DI AND EI DO NOT INCLUDE MOLD PROTRUSION. ALLOWABLE MOLD PROTRUSION IS 0.25 MM ON DI AND EI DIMENSIONS.
- 4. THE TOP OF PACKAGE IS SMALLER THAN THE BOTTOM OF PACKAGE BY 0.15 MILLIMETERS.
- 5. DIMENSION 6 DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.08 MM TOTAL IN EXCESS OF THE 6 DIMENSION AT MAXIMUM MATERIAL CONDITION.
- 6. ALL DIMENSIONS ARE IN MILLIMETERS.
- 7. THIS DUTLINE CONFORMS TO JEDEC PUBLICATION 95, REGISTRATION MS-026.
- 8. LEADS SHALL BE COPLANAR WITHIN .004 INCH.
- MARKING SHOWN IS FOR PACKAGE DRIENTATION REFERENCE ONLY.
- 10. NUMBER OF LEADS ARE SHOWN FOR REFERENCE ONLY.

JEDEC VARIATION					
	BB	A	В	BC	
	MIN.	MAX.	MIN.	MAX.	
Α		1.60		1.60	
A1	0.05	0.15	0.05	0.15	
A2	1.35	1.45	1.35	1.45	
D	8.90	9.10	8.90	9.10	
D1	6.90	7.10	6.90	7.10	
E	8.90	9.10	8.90	9.10	
E1	6.90	7.10	6.90	7.10	
е	0.8	BSC.	0.5 BSC.		
L	0.45	0.75	0.45	0.75	
b	0.30	0.45	0.17	0.27	
b1	0.30	0.40	0.17	0.23	
С	0.09	0.20	0.09	0.20	
c 1	0.09	0.16	0.09	0.16	
N	3	2	4	8	
α	0*	7°	0*	7°	
PKG. CODES	C32-1; C32-2; C48-1; C48-2; C48-3; C48-4F; C48-5; C48-6; C48-9F				

-DRAWING NOT TO SCALE-

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